MC504 Sistemas Operacionais

Gerenciamento de Memória

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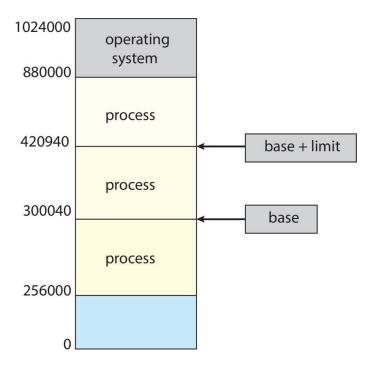
Background

- Program must be brought (from disk) into memory and placed within a process for it to be run
- Main memory and registers are only storage CPU can access directly
- Memory unit only sees a stream of:
 - addresses + read requests, or
 - address + data and write requests
- Register access is done in one CPU clock (or less)
- Main memory can take many cycles, causing a stall
- Cache sits between main memory and CPU registers
- Protection of memory required to ensure correct operation



Protection

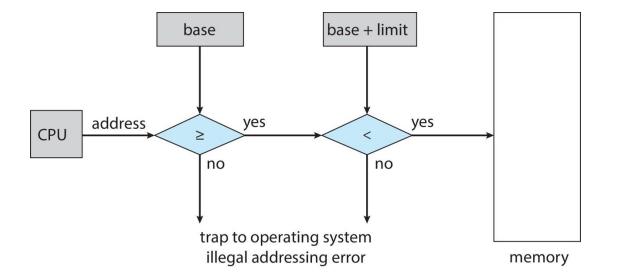
- Need to censure that a process can access only access those addresses in its address space.
- We can provide this protection by using a pair of base and limit registers define the logical address space of a process



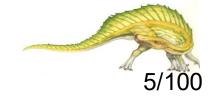


Hardware Address Protection

 CPU must check every memory access generated in user mode to be sure it is between base and limit for that user



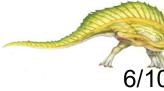
the instructions to loading the base and limit registers are privileged





Address Binding

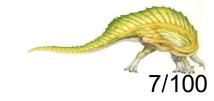
- Programs on disk, ready to be brought into memory to execute form an input queue
 - Without support, must be loaded into address 0000
- Inconvenient to have first user process physical address always at 0000
 - How can it not be?
- Addresses represented in different ways at different stages of a program's life
 - Source code addresses usually symbolic
 - Compiled code addresses bind to relocatable addresses
 - i.e., "14 bytes from beginning of this module"
 - Linker or loader will bind relocatable addresses to absolute addresses
 - ▶ i.e., 74014
 - Each binding maps one address space to another





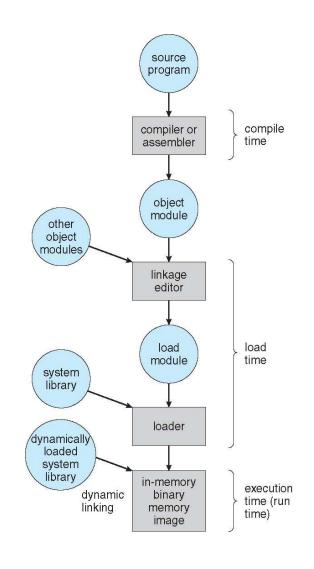
Binding of Instructions and Data to Memory

- Address binding of instructions and data to memory addresses can happen at three different stages
 - Compile time: If memory location known a priori, absolute code can be generated; must recompile code if starting location changes
 - Load time: Must generate relocatable code if memory location is not known at compile time
 - **Execution time**: Binding delayed until run time if the process can be moved during its execution from one memory segment to another
 - Need hardware support for address maps (e.g., base and limit registers)





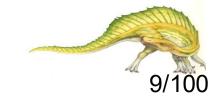
Multistep Processing of a User Program





Logical vs. Physical Address Space

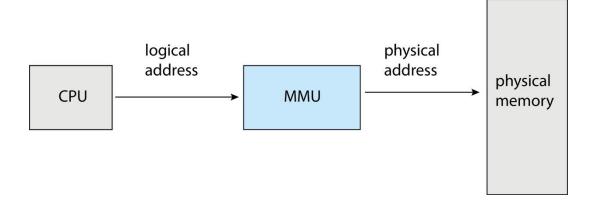
- The concept of a logical address space that is bound to a separate physical address space is central to proper memory management
 - Logical address generated by the CPU; also referred to as virtual address
 - Physical address address seen by the memory unit
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme
- Logical address space is the set of all logical addresses generated by a program
- Physical address space is the set of all physical addresses generated by a program





Memory-Management Unit (MMU)

Hardware device that at run time maps virtual to physical address

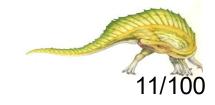


Many methods possible, covered in the rest of this chapter



Memory-Management Unit (Cont.)

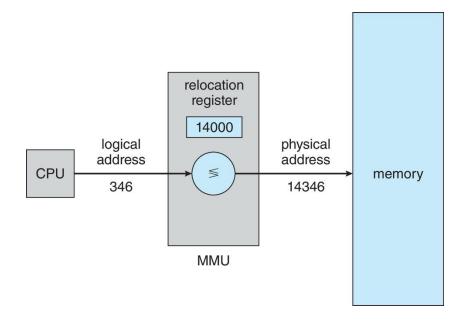
- Consider simple scheme. which is a generalization of the baseregister scheme.
- The base register now called relocation register
- The value in the relocation register is added to every address generated by a user process at the time it is sent to memory
- The user program deals with logical addresses; it never sees the real physical addresses
 - Execution-time binding occurs when reference is made to location in memory
 - Logical address bound to physical addresses





Memory-Management Unit (Cont.)

- Consider simple scheme. which is a generalization of the baseregister scheme.
- The base register now called relocation register
- The value in the relocation register is added to every address generated by a user process at the time it is sent to memory





Contiguous Allocation

- Main memory must support both OS and user processes
- Limited resource, must allocate efficiently
- Contiguous allocation is one early method
- Main memory usually into two partitions:
 - Resident operating system, usually held in low memory with interrupt vector
 - User processes then held in high memory
 - Each process contained in single contiguous section of memory

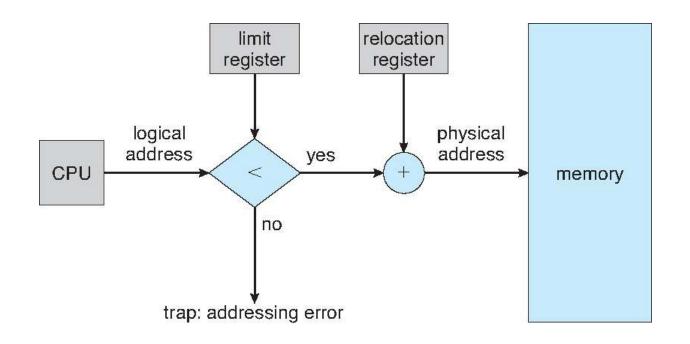


Contiguous Allocation (Cont.)

- Relocation registers used to protect user processes from each other, and from changing operating-system code and data
 - Base register contains value of smallest physical address
 - Limit register contains range of logical addresses each logical address must be less than the limit register
 - MMU maps logical address dynamically
 - Can then allow actions such as kernel code being **transient** and kernel changing size



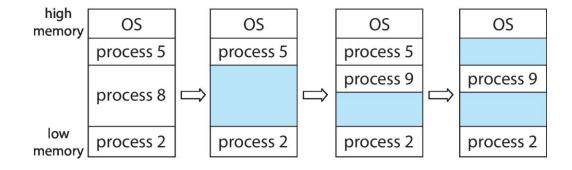
Hardware Support for Relocation and Limit Registers





Variable Partition

- Multiple-partition allocation
 - Degree of multiprogramming limited by number of partitions
 - Variable-partition sizes for efficiency (sized to a given process' needs)
 - Hole block of available memory; holes of various size are scattered throughout memory
 - When a process arrives, it is allocated memory from a hole large enough to accommodate it
 - Process exiting frees its partition, adjacent free partitions combined
 - Operating system maintains information about:
 a) allocated partitions b) free partitions (hole)



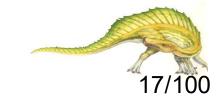


Dynamic Storage-Allocation Problem

How to satisfy a request of size *n* from a list of free holes?

- First-fit: Allocate the *first* hole that is big enough
- Best-fit: Allocate the smallest hole that is big enough; must search entire list, unless ordered by size
 - Produces the smallest leftover hole
- Worst-fit: Allocate the *largest* hole; must also search entire list
 - Produces the largest leftover hole

First-fit and best-fit better than worst-fit in terms of speed and storage utilization





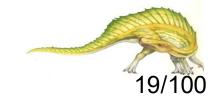
Fragmentation

- **External Fragmentation** total memory space exists to satisfy a request, but it is not contiguous
- **Internal Fragmentation** allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used
- First fit analysis reveals that given *N* blocks allocated, 0.5 *N* blocks lost to fragmentation
 - 1/3 may be unusable -> 50-percent rule



Fragmentation (Cont.)

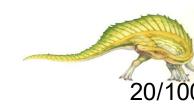
- Reduce external fragmentation by compaction
 - Shuffle memory contents to place all free memory together in one large block
 - Compaction is possible *only* if relocation is dynamic, and is done at execution time
 - I/O problem
 - Latch job in memory while it is involved in I/O
 - Do I/O only into OS buffers
- Now consider that backing store has same fragmentation problems





Paging

- Physical address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available
 - Avoids external fragmentation
 - Avoids problem of varying sized memory chunks
- Divide physical memory into fixed-sized blocks called frames
 - Size is power of 2, between 512 bytes and 16 Mbytes
- Divide logical memory into blocks of same size called pages
- Keep track of all free frames
- To run a program of size **N** pages, need to find **N** free frames and load program
- Set up a page table to translate logical to physical addresses
- Backing store likewise split into pages
- Still have Internal fragmentation



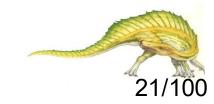


Address Translation Scheme

- Address generated by CPU is divided into:
 - Page number (p) used as an index into a page table which contains base address of each page in physical memory
 - Page offset (d) combined with base address to define the physical memory address that is sent to the memory unit

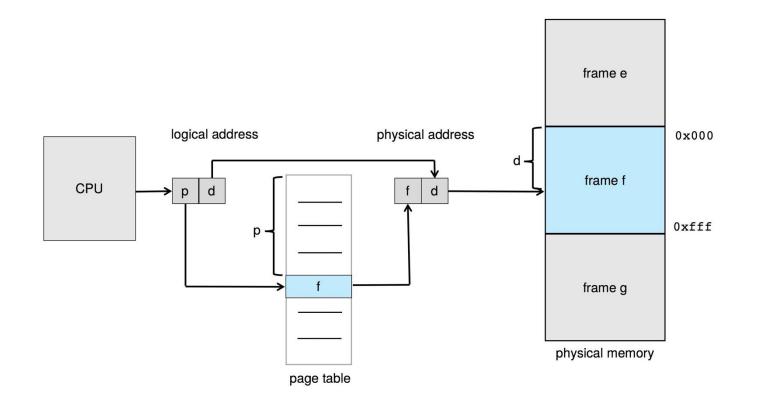
page number	page offset
р	d
m -n	n

For given logical address space 2^m and page size 2ⁿ



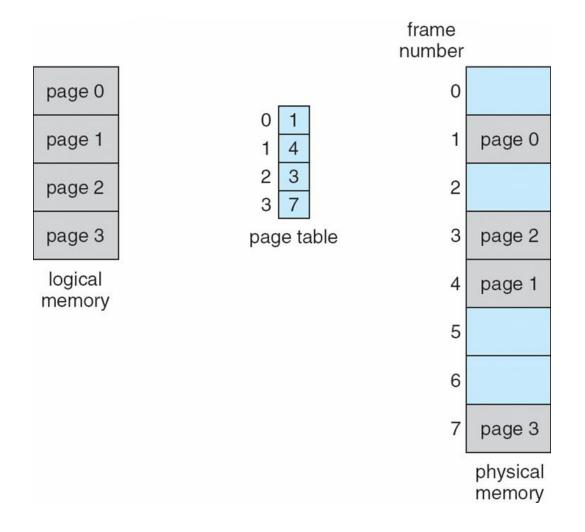


Paging Hardware





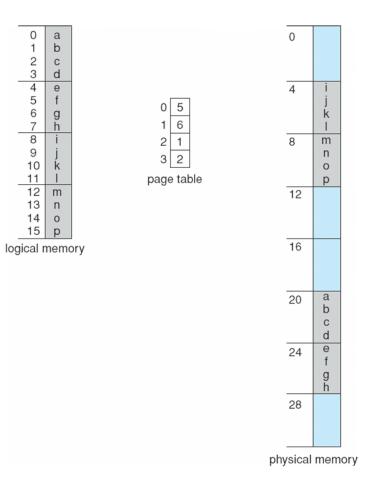
Paging Model of Logical and Physical Memory





Paging Example

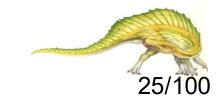
 Logical address: n = 2 and m = 4. Using a page size of 4 bytes and a physical memory of 32 bytes (8 pages)





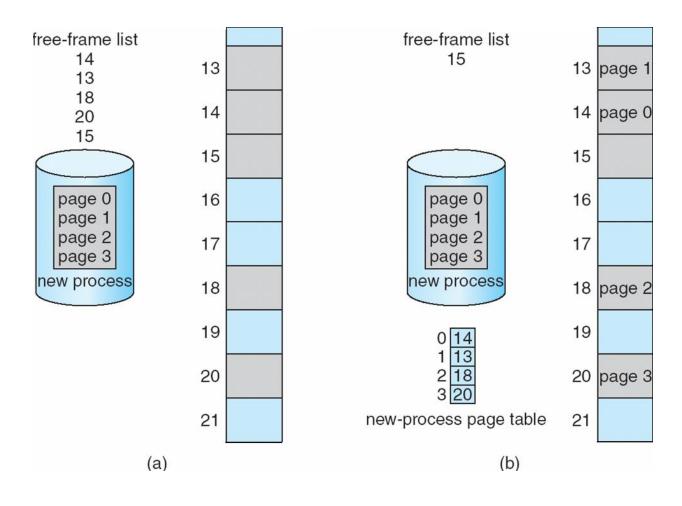
Paging -- Calculating internal fragmentation

- Page size = 2,048 bytes
- Process size = 72,766 bytes
- 35 pages + 1,086 bytes
- Internal fragmentation of 2,048 1,086 = 962 bytes
- Worst case fragmentation = 1 frame 1 byte
- On average fragmentation = 1 / 2 frame size
- So small frame sizes desirable?
- But each page table entry takes memory to track
- Page sizes growing over time
 - Solaris supports two page sizes 8 KB and 4 MB



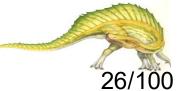


Free Frames



Before allocation

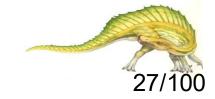
After allocation





Implementation of Page Table

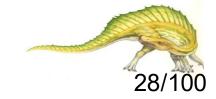
- Page table is kept in main memory
 - Page-table base register (PTBR) points to the page table
 - Page-table length register (PTLR) indicates size of the page table
- In this scheme every data/instruction access requires two memory accesses
 - One for the page table and one for the data / instruction
- The two-memory access problem can be solved by the use of a special fast-lookup hardware cache called **translation look-aside buffers** (TLBs) (also called **associative memory**).





Translation Look-Aside Buffer

- Some TLBs store address-space identifiers (ASIDs) in each TLB entry – uniquely identifies each process to provide addressspace protection for that process
 - Otherwise need to flush at every context switch
- TLBs typically small (64 to 1,024 entries)
- On a TLB miss, value is loaded into the TLB for faster access next time
 - Replacement policies must be considered
 - Some entries can be wired down for permanent fast access





Hardware

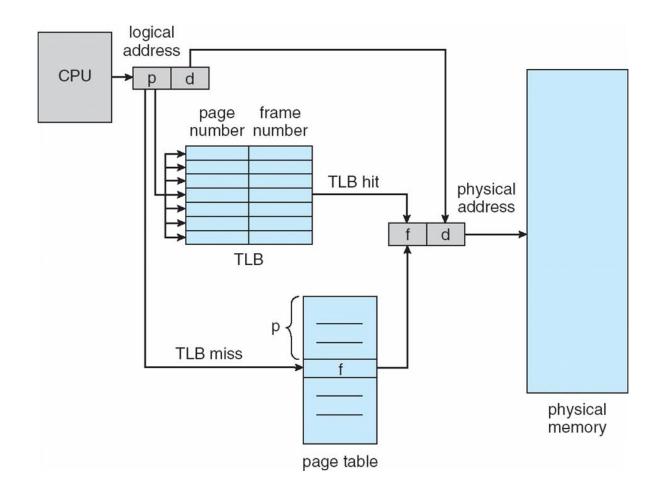
Associative memory – parallel search

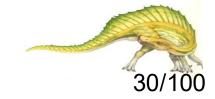
Page #	Frame #

- Address translation (p, d)
 - If p is in associative register, get frame # out
 - Otherwise get frame # from page table in memory



Paging Hardware With TLB

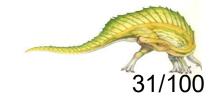






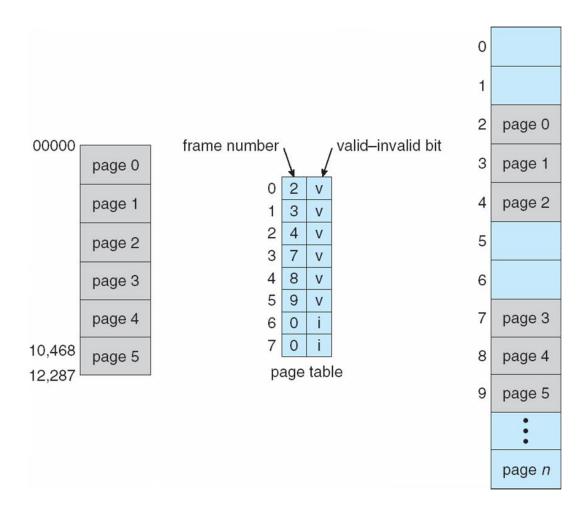
Memory Protection

- Memory protection implemented by associating protection bit with each frame to indicate if read-only or read-write access is allowed
 - Can also add more bits to indicate page execute-only, and so on
- Valid-invalid bit attached to each entry in the page table:
 - "valid" indicates that the associated page is in the process' logical address space, and is thus a legal page
 - "invalid" indicates that the page is not in the process' logical address space
 - Or use page-table length register (PTLR)
- Any violations result in a trap to the kernel





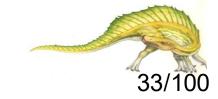
Valid (v) or Invalid (i) Bit In A Page Table





Dynamic Loading

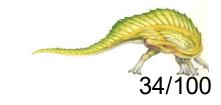
- The entire program does need to be in memory to execute
- Routine is not loaded until it is called
- Better memory-space utilization; unused routine is never loaded
- All routines kept on disk in relocatable load format
- Useful when large amounts of code are needed to handle infrequently occurring cases
- No special support from the operating system is required
 - Implemented through program design
 - OS can help by providing libraries to implement dynamic loading





Dynamic Linking

- Static linking system libraries and program code combined by the loader into the binary program image
- Dynamic linking –linking postponed until execution time
- Small piece of code, stub, used to locate the appropriate memoryresident library routine
- Stub replaces itself with the address of the routine, and executes the routine
- Operating system checks if routine is in processes' memory address
 - If not in address space, add to address space
- Dynamic linking is particularly useful for libraries
- System also known as shared libraries
- Consider applicability to patching system libraries
 - Versioning may be needed





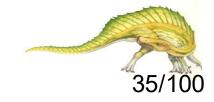
Shared Pages

Shared code

- One copy of read-only (reentrant) code shared among processes (i.e., text editors, compilers, window systems)
- Similar to multiple threads sharing the same process space
- Also useful for interprocess communication if sharing of read-write pages is allowed

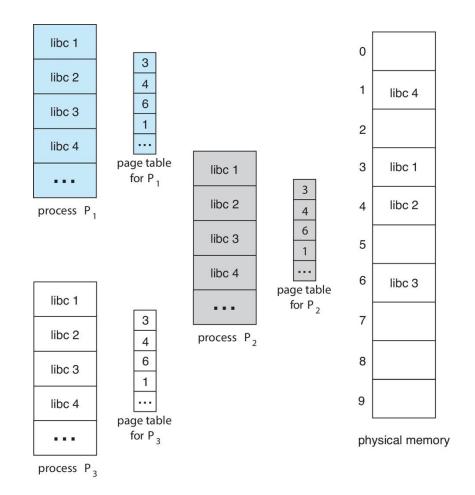
Private code and data

- Each process keeps a separate copy of the code and data
- The pages for the private code and data can appear anywhere in the logical address space





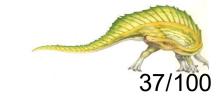
Shared Pages Example





Swapping

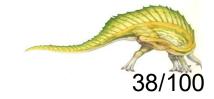
- A process can be swapped temporarily out of memory to a backing store, and then brought back into memory for continued execution
 - Total physical memory space of processes can exceed physical memory
- Backing store fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images
- Roll out, roll in swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed
- Major part of swap time is transfer time; total transfer time is directly proportional to the amount of memory swapped
- System maintains a ready queue of ready-to-run processes which have memory images on disk





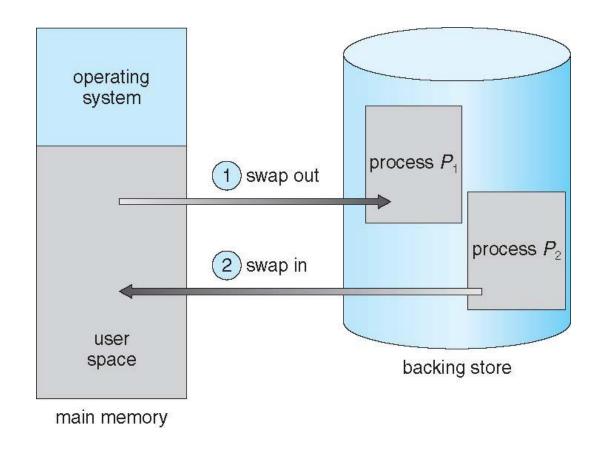
Swapping (Cont.)

- Does the swapped out process need to swap back in to same physical addresses?
- Depends on address binding method
 - Plus consider pending I/O to / from process memory space
- Modified versions of swapping are found on many systems (i.e., UNIX, Linux, and Windows)
 - Swapping normally disabled
 - Started if more than threshold amount of memory allocated
 - Disabled again once memory demand reduced below threshold





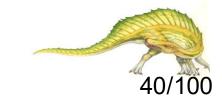
Schematic View of Swapping





Context Switch Time including Swapping

- If next processes to be put on CPU is not in memory, need to swap out a process and swap in target process
- Context switch time can then be very high
- 100MB process swapping to hard disk with transfer rate of 50MB/sec
 - Swap out time of 2000 ms
 - Plus swap in of same sized process
 - Total context switch swapping component time of 4000ms (4 seconds)
- Can reduce if reduce size of memory swapped by knowing how much memory really being used
 - System calls to inform OS of memory use via request_memory() and release_memory()





Context Switch Time and Swapping (Cont.)

- Other constraints as well on swapping
 - Pending I/O can't swap out as I/O would occur to wrong process
 - Or always transfer I/O to kernel space, then to I/O device
 - Known as double buffering, adds overhead
- Standard swapping not used in modern operating systems
 - But modified version common
 - Swap only when free memory extremely low

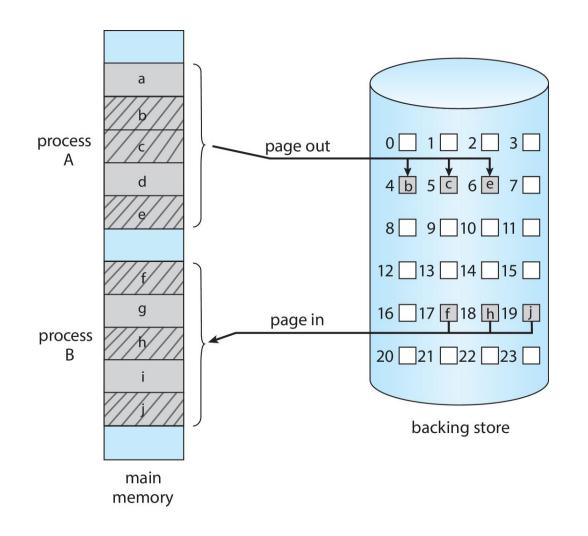


Swapping on Mobile Systems

- Not typically supported
 - Flash memory based
 - Small amount of space
 - Limited number of write cycles
 - Poor throughput between flash memory and CPU on mobile platform
- Instead use other methods to free memory if low
 - iOS *asks* apps to voluntarily relinquish allocated memory
 - Read-only data thrown out and reloaded from flash if needed
 - Failure to free can result in termination
 - Android terminates apps if low free memory, but first writes application state to flash for fast restart



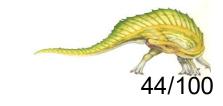
Swapping with Paging





Background

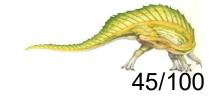
- Code needs to be in memory to execute, but entire program rarely used
 - Error code, unusual routines, large data structures
- Entire program code not needed at same time
- Consider ability to execute partially-loaded program
 - Program no longer constrained by limits of physical memory
 - Each program takes less memory while running -> more programs run at the same time
 - Increased CPU utilization and throughput with no increase in response time or turnaround time
 - Less I/O needed to load or swap programs into memory -> each user program runs faster





Virtual memory

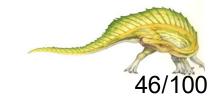
- Virtual memory separation of user logical memory from physical memory
 - Only part of the program needs to be in memory for execution
 - Logical address space can therefore be much larger than physical address space
 - Allows address spaces to be shared by several processes
 - Allows for more efficient process creation
 - More programs running concurrently
 - Less I/O needed to load or swap processes





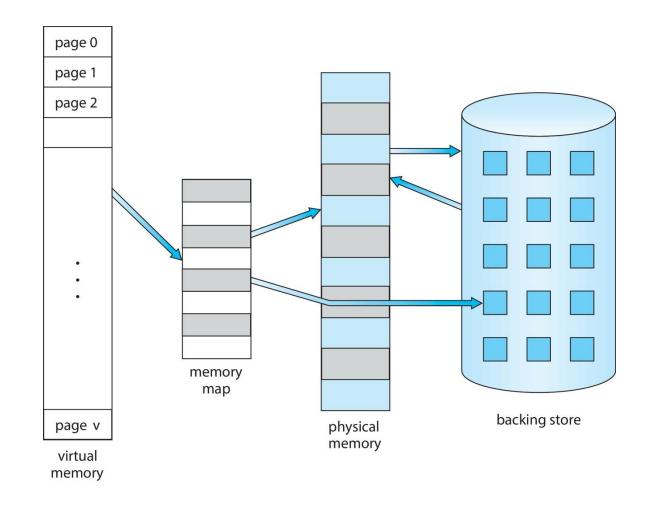
Virtual memory (Cont.)

- Virtual address space logical view of how process is stored in memory
 - Usually start at address 0, contiguous addresses until end of space
 - Meanwhile, physical memory organized in page frames
 - MMU must map logical to physical
- Virtual memory can be implemented via:
 - Demand paging
 - Demand segmentation





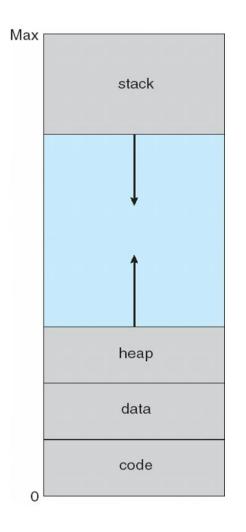
Virtual Memory That is Larger Than Physical Memory





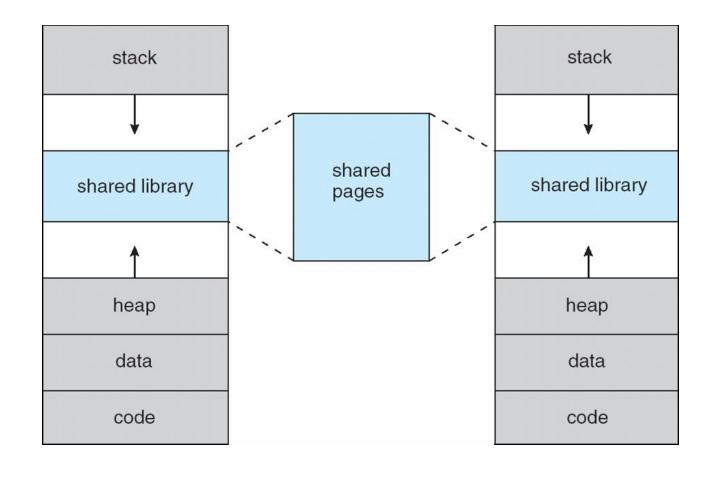
Virtual-address Space

- Usually design logical address space for stack to start at Max logical address and grow "down" while heap grows "up"
 - Maximizes address space use
 - Unused address space between the two is hole
 - No physical memory needed until heap or stack grows to a given new page
- Enables sparse address spaces with holes left for growth, dynamically linked libraries, etc.
- System libraries shared via mapping into virtual address space
- Shared memory by mapping pages readwrite into virtual address space
- Pages can be shared during fork(),
 speeding process creation





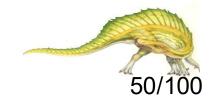
Shared Library Using Virtual Memory





Demand Paging

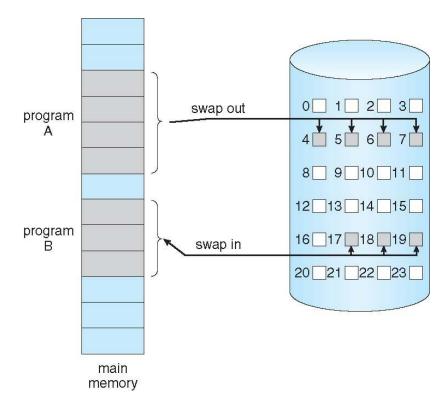
- Could bring entire process into memory at load time
- Or bring a page into memory only when it is needed
 - Less I/O needed, no unnecessary I/O
 - Less memory needed
 - Faster response
 - More users
- Similar to paging system with swapping (diagram on right)
- Page is needed ⇒ reference to it
 - invalid reference ⇒ abort
 - not-in-memory ⇒ bring to memory
- Lazy swapper never swaps a page into memory unless page will be needed
 - Swapper that deals with pages is a pager

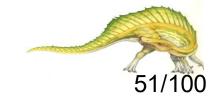




Demand Paging

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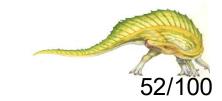






Basic Concepts

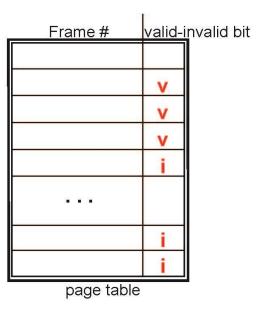
- With swapping, pager guesses which pages will be used before swapping out again
- Instead, pager brings in only those pages into memory
- How to determine that set of pages?
 - Need new MMU functionality to implement demand paging
- If pages needed are already memory resident
 - No difference from non demand-paging
- If page needed and not memory resident
 - Need to detect and load the page into memory from storage
 - Without changing program behavior
 - Without programmer needing to change code



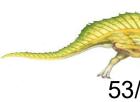


Valid-Invalid Bit

- With each page table entry a valid–invalid bit is associated
 (v ⇒ in-memory memory resident, i ⇒ not-in-memory)
- Initially valid—invalid bit is set to i on all entries
- Example of a page table snapshot:

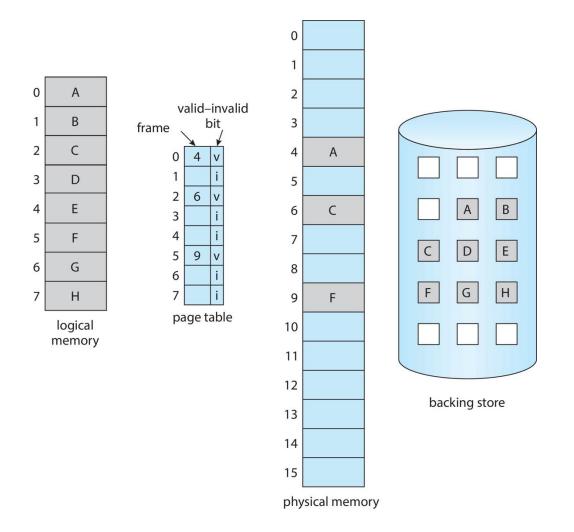


 During MMU address translation, if valid–invalid bit in page table entry is i ⇒ page fault





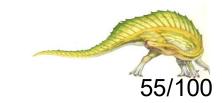
Page Table When Some Pages Are Not in Main Memory





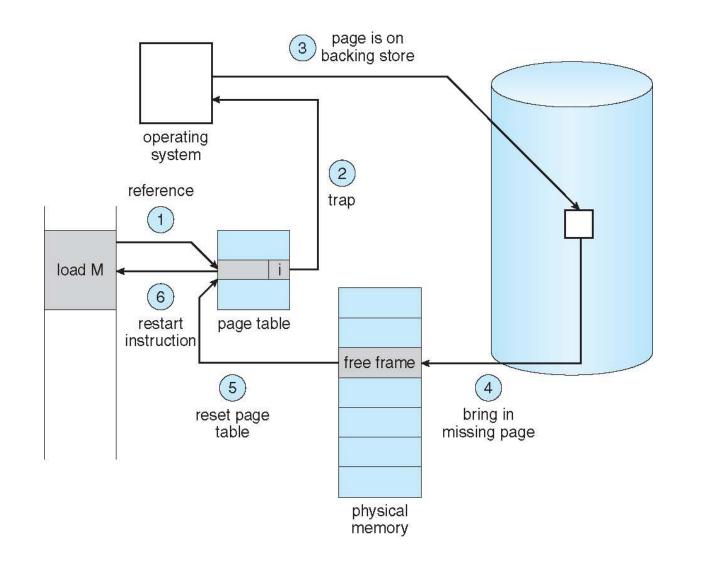
Steps in Handling Page Fault

- 1. If there is a reference to a page, first reference to that page will trap to operating system
 - Page fault
- 2. Operating system looks at another table to decide:
 - Invalid reference ⇒ abort
 - Just not in memory
- 3. Find free frame
- 4. Swap page into frame via scheduled disk operation
- 5. Reset tables to indicate page now in memory Set validation bit = v
- 6. Restart the instruction that caused the page fault





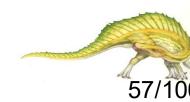
Steps in Handling a Page Fault (Cont.)





Aspects of Demand Paging

- Extreme case start process with no pages in memory
 - OS sets instruction pointer to first instruction of process, nonmemory-resident -> page fault
 - And for every other process pages on first access
 - Pure demand paging
- Actually, a given instruction could access multiple pages -> multiple page faults
 - Consider fetch and decode of instruction which adds 2 numbers from memory and stores result back to memory
 - Pain decreased because of locality of reference
- Hardware support needed for demand paging
 - Page table with valid / invalid bit
 - Secondary memory (swap device with swap space)
 - Instruction restart





Free-Frame List

- When a page fault occurs, the operating system must bring the desired page from secondary storage into main memory.
- Most operating systems maintain a free-frame list -- a pool of free frames for satisfying such requests.

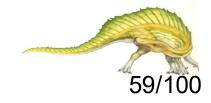
head
$$\longrightarrow$$
 7 \longrightarrow 97 \longrightarrow 15 \longrightarrow 126 \cdots \longrightarrow 75

- Operating system typically allocate free frames using a technique known as zero-fill-on-demand -- the content of the frames zeroedout before being allocated.
- When a system starts up, all available memory is placed on the freeframe list.



Stages in Demand Paging – Worse Case

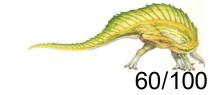
- 1. Trap to the operating system
- 2. Save the user registers and process state
- 3. Determine that the interrupt was a page fault
- 4. Check that the page reference was legal and determine the location of the page on the disk
- 5. Issue a read from the disk to a free frame:
 - a) Wait in a queue for this device until the read request is serviced
 - b) Wait for the device seek and/or latency time
 - c) Begin the transfer of the page to a free frame





Stages in Demand Paging (Cont.)

- 6. While waiting, allocate the CPU to some other user
- 7. Receive an interrupt from the disk I/O subsystem (I/O completed)
- 8. Save the registers and process state for the other user
- 9. Determine that the interrupt was from the disk
- 10. Correct the page table and other tables to show page is now in memory
- 11. Wait for the CPU to be allocated to this process again
- 12. Restore the user registers, process state, and new page table, and then resume the interrupted instruction



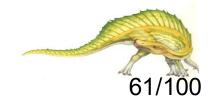


Performance of Demand Paging

- Three major activities
 - Service the interrupt careful coding means just several hundred instructions needed
 - Read the page lots of time
 - Restart the process again just a small amount of time
- Page Fault Rate $0 \le p \le 1$
 - if p = 0 no page faults
 - if p = 1, every reference is a fault
- Effective Access Time (EAT)

$$EAT = (1 - p) x memory access$$

- + p (page fault overhead
- + swap page out
- + swap page in)



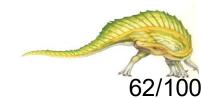


Demand Paging Example

- Memory access time = 200 nanoseconds
- Average page-fault service time = 8 milliseconds
- EAT = $(1 p) \times 200 + p (8 \text{ milliseconds})$ = $(1 - p \times 200 + p \times 8,000,000$ = $200 + p \times 7,999,800$
- If one access out of 1,000 causes a page fault, then EAT = 8.2 microseconds.

This is a slowdown by a factor of 40!!

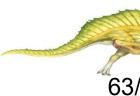
- If want performance degradation < 10 percent</p>
 - 220 > 200 + 7,999,800 x p
 20 > 7,999,800 x p
 - p < .0000025
 - < one page fault in every 400,000 memory accesses





Demand Paging Optimizations

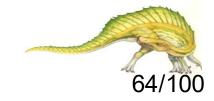
- Swap space I/O faster than file system I/O even if on the same device
 - Swap allocated in larger chunks, less management needed than file system
- Copy entire process image to swap space at process load time
 - Then page in and out of swap space
 - Used in older BSD Unix
- Demand page in from program binary on disk, but discard rather than paging out when freeing frame
 - Used in Solaris and current BSD
 - Still need to write to swap space
 - Pages not associated with a file (like stack and heap) anonymous memory
 - Pages modified in memory but not yet written back to the file system
- Mobile systems
 - Typically don't support swapping
 - Instead, demand page from file system and reclaim read-only pages (such as code)





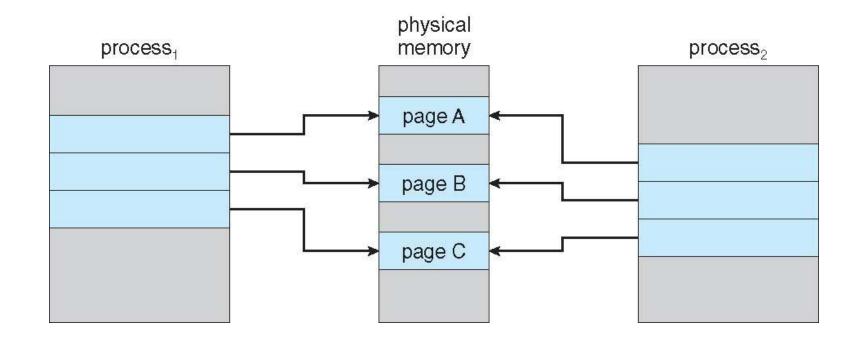
Copy-on-Write

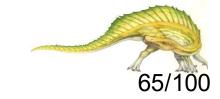
- Copy-on-Write (COW) allows both parent and child processes to initially share the same pages in memory
 - If either process modifies a shared page, only then is the page copied
- COW allows more efficient process creation as only modified pages are copied
- In general, free pages are allocated from a pool of zero-fill-on-demand pages
 - Pool should always have free frames for fast demand page execution
 - Don't want to have to free a frame as well as other processing on page fault
 - Why zero-out a page before allocating it?
- vfork() variation on fork() system call has parent suspend and child using copy-on-write address space of parent
 - Designed to have child call exec()
 - Very efficient





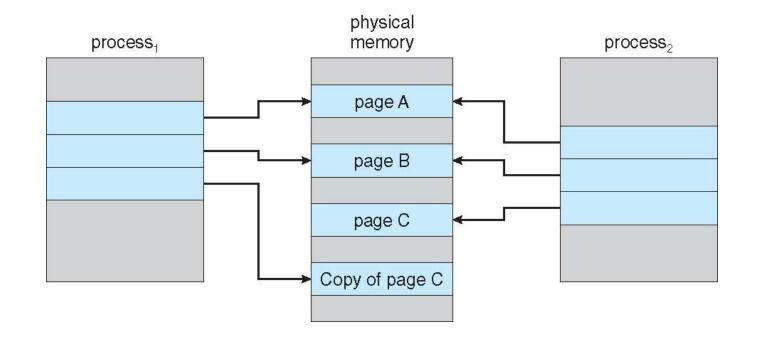
Before Process 1 Modifies Page C







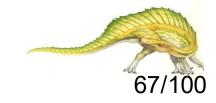
After Process 1 Modifies Page C





What Happens if There is no Free Frame?

- Used up by process pages
- Also in demand from the kernel, I/O buffers, etc.
- How much to allocate to each?
- Page replacement find some page in memory, but not really in use, page it out
 - Algorithm terminate? swap out? replace the page?
 - Performance want an algorithm which will result in minimum number of page faults
- Same page may be brought into memory several times



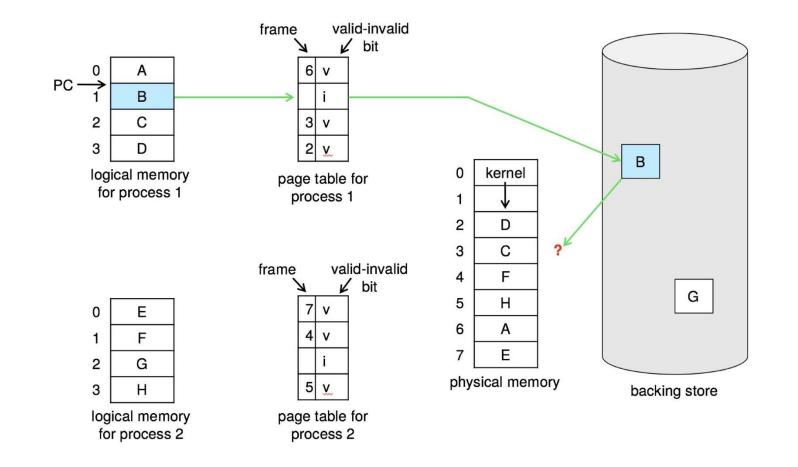


Page Replacement

- Prevent over-allocation of memory by modifying page-fault service routine to include page replacement
- Use modify (dirty) bit to reduce overhead of page transfers only modified pages are written to disk
- Page replacement completes separation between logical memory and physical memory – large virtual memory can be provided on a smaller physical memory



Need For Page Replacement

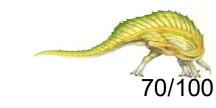




Basic Page Replacement

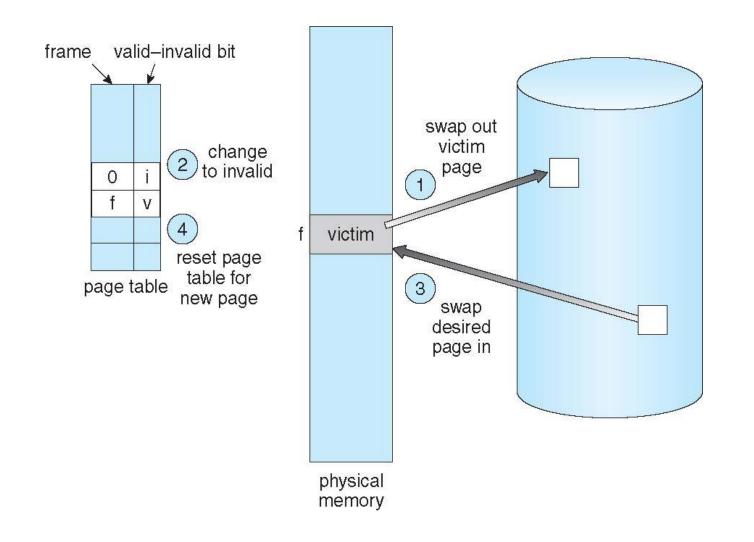
- 1. Find the location of the desired page on disk
- 2. Find a free frame:
 - If there is a free frame, use it
 - If there is no free frame, use a page replacement algorithm to select a **victim frame**
 - Write victim frame to disk if dirty
- 3. Bring the desired page into the (newly) free frame; update the page and frame tables
- 4. Continue the process by restarting the instruction that caused the trap

Note now potentially 2 page transfers for page fault – increasing EAT





Page Replacement







Page and Frame Replacement Algorithms

- Frame-allocation algorithm determines
 - How many frames to give each process
 - Which frames to replace
- Page-replacement algorithm
 - Want lowest page-fault rate on both first access and re-access
- Evaluate algorithm by running it on a particular string of memory references (reference string) and computing the number of page faults on that string
 - String is just page numbers, not full addresses
 - Repeated access to the same page does not cause a page fault
 - Results depend on number of frames available
- In all our examples, the reference string of referenced page numbers is

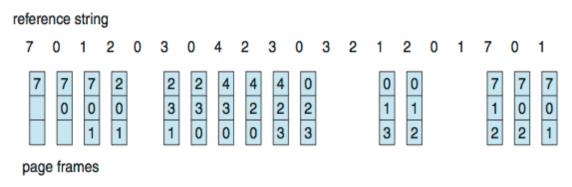
7,0,1,2,0,3,0,4,2,3,0,3,0,3,2,1,2,0,1,7,0,1





First-In-First-Out (FIFO) Algorithm

- Reference string: 7,0,1,2,0,3,0,4,2,3,0,3,0,3,2,1,2,0,1,7,0,1
- 3 frames (3 pages can be in memory at a time per process)

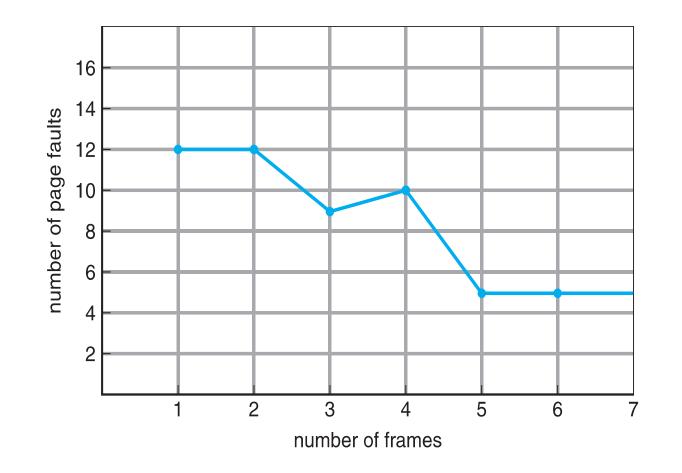


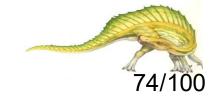
15 page faults

- Can vary by reference string: consider 1,2,3,4,1,2,5,1,2,3,4,5
 - Adding more frames can cause more page faults!
 - Belady's Anomaly
- How to track ages of pages?
 - Just use a FIFO queue



FIFO Illustrating Belady's Anomaly

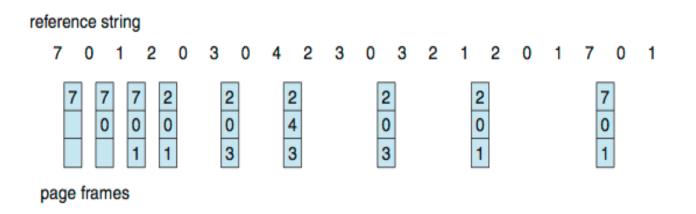






Optimal Algorithm

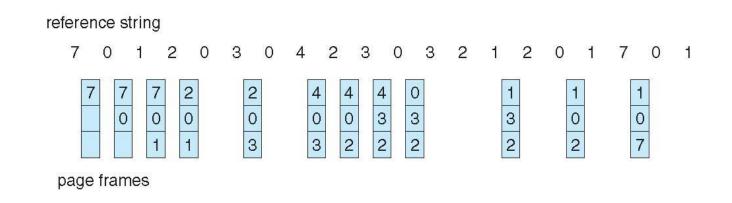
- Replace page that will not be used for longest period of time
 - 9 is optimal for the example
- How do you know this?
 - Can't read the future
- Used for measuring how well your algorithm performs



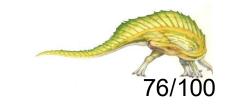


Least Recently Used (LRU) Algorithm

- Use past knowledge rather than future
- Replace page that has not been used in the most amount of time
- Associate time of last use with each page



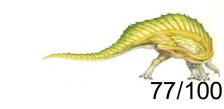
- 12 faults better than FIFO but worse than OPT
- Generally good algorithm and frequently used
- But how to implement?





LRU Algorithm (Cont.)

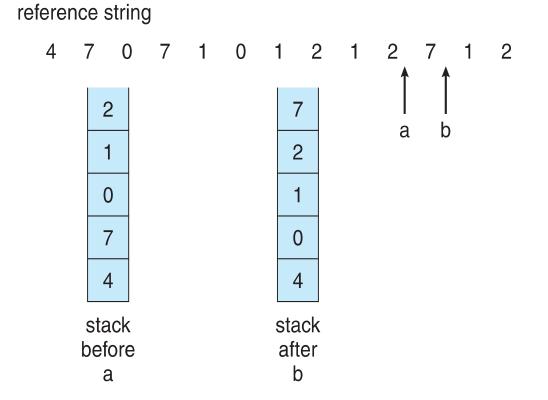
- Counter implementation
 - Every page entry has a counter; every time page is referenced through this entry, copy the clock into the counter
 - When a page needs to be changed, look at the counters to find smallest value
 - Search through table needed
- Stack implementation
 - Keep a stack of page numbers in a double link form:
 - Page referenced:
 - move it to the top
 - requires 6 pointers to be changed
 - But each update more expensive
 - No search for replacement





LRU Algorithm (Cont.)

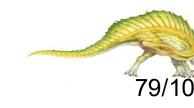
- LRU and OPT are cases of stack algorithms that don't have Belady's Anomaly
- Use Of A Stack to Record Most Recent Page References





LRU Approximation Algorithms

- LRU needs special hardware and still slow
- Reference bit
 - With each page associate a bit, initially = 0
 - When page is referenced bit set to 1
 - Replace any with reference bit = 0 (if one exists)
 - We do not know the order, however

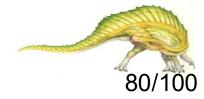




LRU Approximation Algorithms (cont.)

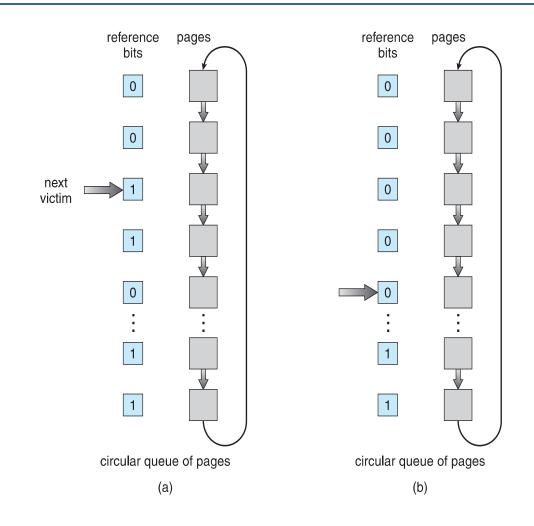
Second-chance algorithm

- Generally FIFO, plus hardware-provided reference bit
- **Clock** replacement
- If page to be replaced has
 - ▶ Reference bit = 0 -> replace it
 - reference bit = 1 then:
 - set reference bit 0, leave page in memory
 - replace next page, subject to same rules





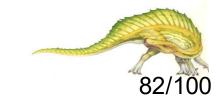
Second-chance Algorithm





Enhanced Second-Chance Algorithm

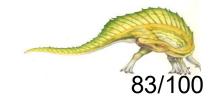
- Improve algorithm by using reference bit and modify bit (if available) in concert
- Take ordered pair (reference, modify):
 - (0, 0) neither recently used not modified best page to replace
 - (0, 1) not recently used but modified not quite as good, must write out before replacement
 - (1, 0) recently used but clean probably will be used again soon
 - (1, 1) recently used and modified probably will be used again soon and need to write out before replacement
- When page replacement called for, use the clock scheme but use the four classes replace page in lowest non-empty class
 - Might need to search circular queue several times





Counting Algorithms

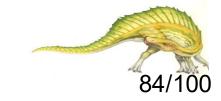
- Keep a counter of the number of references that have been made to each page
 - Not common
- Lease Frequently Used (LFU) Algorithm:
 - Replaces page with smallest count
- Most Frequently Used (MFU) Algorithm:
 - Based on the argument that the page with the smallest count was probably just brought in and has yet to be used





Page-Buffering Algorithms

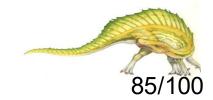
- Keep a pool of free frames, always
 - Then frame available when needed, not found at fault time
 - Read page into free frame and select victim to evict and add to free pool
 - When convenient, evict victim
- Possibly, keep list of modified pages
 - When backing store otherwise idle, write pages there and set to non-dirty
- Possibly, keep free frame contents intact and note what is in them
 - If referenced again before reused, no need to load contents again from disk
 - Generally useful to reduce penalty if wrong victim frame selected





Applications and Page Replacement

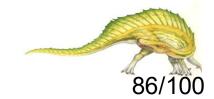
- All of these algorithms have OS guessing about future page access
- Some applications have better knowledge i.e. databases
- Memory intensive applications can cause double buffering
 - OS keeps copy of page in memory as I/O buffer
 - Application keeps page in memory for its own work
- Operating system can give direct access to the disk, getting out of the way of the applications
 - Raw disk mode
- Bypasses buffering, locking, etc.





Allocation of Frames

- Each process needs *minimum* number of frames
- Example: IBM 370 6 pages to handle SS MOVE instruction:
 - instruction is 6 bytes, might span 2 pages
 - 2 pages to handle from
 - 2 pages to handle to
- Maximum of course is total frames in the system
- Two major allocation schemes
 - fixed allocation
 - priority allocation
- Many variations





Fixed Allocation

- Equal allocation For example, if there are 100 frames (after allocating frames for the OS) and 5 processes, give each process 20 frames
 - Keep some as free frame buffer pool
- Proportional allocation Allocate according to the size of process
 - Dynamic as degree of multiprogramming, process sizes change

$$-s_i = \text{size of process } p_i$$

$$-S = \sum s_i$$

$$-m = total number of frames$$

$$a_i = \text{allocation for } p_i = \frac{s_i}{S} \times m$$

$$m = 64$$

$$s_1 = 10$$

$$s_2 = 127$$

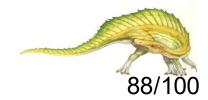
$$a_1 = \frac{10}{137} \square 62 \square 4$$

$$a_2 = \frac{127}{137} \square 62 \square 57$$



Global vs. Local Allocation

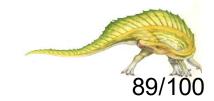
- Global replacement process selects a replacement frame from the set of all frames; one process can take a frame from another
 - But then process execution time can vary greatly
 - But greater throughput so more common
- Local replacement each process selects from only its own set of allocated frames
 - More consistent per-process performance
 - But possibly underutilized memory





Thrashing

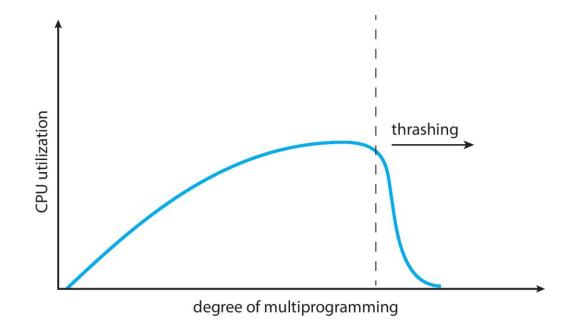
- If a process does not have "enough" pages, the page-fault rate is very high
 - Page fault to get page
 - Replace existing frame
 - But quickly need replaced frame back
 - This leads to:
 - Low CPU utilization
 - Operating system thinking that it needs to increase the degree of multiprogramming
 - Another process added to the system

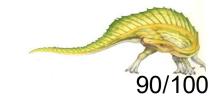




Thrashing (Cont.)

Thrashing. A process is busy swapping pages in and out





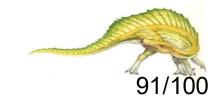


Demand Paging and Thrashing

Why does demand paging work?

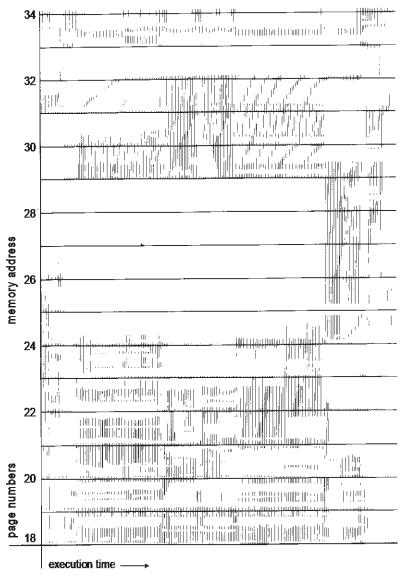
Locality model

- Process migrates from one locality to another
- Localities may overlap
- Why does thrashing occur?
 - Σ size of locality > total memory size
- Limit effects by using local or priority page replacement





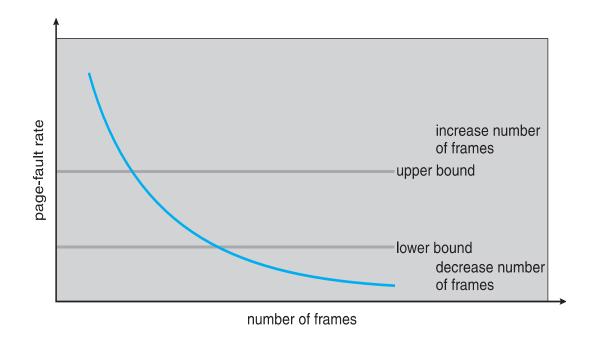
Locality In A Memory-Reference Pattern





Page-Fault Frequency

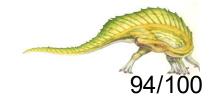
- Establish "acceptable" page-fault frequency (PFF) rate and use local replacement policy
 - If actual rate too low, process loses frame
 - If actual rate too high, process gains frame





Prepaging

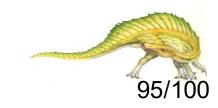
- To reduce the large number of page faults that occurs at process startup
- Prepage all or some of the pages a process will need, before they are referenced
- But if prepaged pages are unused, I/O and memory was wasted
- Assume s pages are prepaged and α of the pages is used
 - Is cost of $\mathbf{s} * \boldsymbol{\alpha}$ save pages faults > or < than the cost of prepaging $\mathbf{s} * (1 \boldsymbol{\alpha})$ unnecessary pages?
 - α near zero \Rightarrow prepaging loses





Page Size

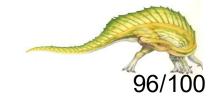
- Sometimes OS designers have a choice
 - Especially if running on custom-built CPU
- Page size selection must take into consideration:
 - Fragmentation
 - Page table size
 - Resolution
 - I/O overhead
 - Number of page faults
 - Locality
 - TLB size and effectiveness
- Always power of 2, usually in the range 2¹² (4,096 bytes) to 2²² (4,194,304 bytes)
- On average, growing over time





TLB Reach

- TLB Reach The amount of memory accessible from the TLB
- TLB Reach = (TLB Size) X (Page Size)
- Ideally, the working set of each process is stored in the TLB
 - Otherwise there is a high degree of page faults
- Increase the Page Size
 - This may lead to an increase in fragmentation as not all applications require a large page size
- Provide Multiple Page Sizes
 - This allows applications that require larger page sizes the opportunity to use them without an increase in fragmentation





Program Structure

- Program structure
 - int[128,128] data;
 - Each row is stored in one page
 - Program 1

 $128 \times 128 = 16,384$ page faults

Program 2

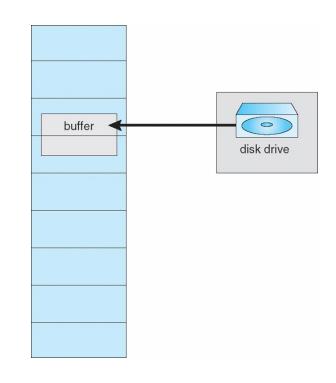
128 page faults

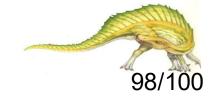




I/O interlock

- I/O Interlock Pages must sometimes be locked into memory
- Consider I/O Pages that are used for copying a file from a device must be locked from being selected for eviction by a page replacement algorithm
- **Pinning** of pages to lock into memory

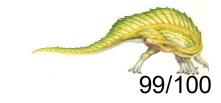




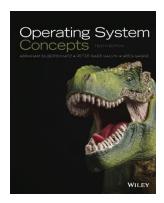


Windows

- Uses demand paging with clustering. Clustering brings in pages surrounding the faulting page
- Processes are assigned working set minimum and working set maximum
- Working set minimum is the minimum number of pages the process is guaranteed to have in memory
- A process may be assigned as many pages up to its working set maximum
- When the amount of free memory in the system falls below a threshold, automatic working set trimming is performed to restore the amount of free memory
- Working set trimming removes pages from processes that have pages in excess of their working set minimum



Bibliografia



Capítulos 9 e 10.



Capítulo 3.