# **Rank Diffusion for Context-Based Image Retrieval**

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# ABSTRACT

This paper presents an efficient diffusion-based re-ranking approach. The proposed method propagates contextual information defined in terms of top-ranked objects of ranked lists in a diffusion process. That makes the method suitable for large scale real-world collections. Experiments were conducted considering public image collections, several descriptors, and comparisons with state-of-the-art methods. Experimental results demonstrate that the proposed method provides high effectiveness gains with low computational costs.

#### Keywords

content-based image retrieval; unsupervised distance learning; rank diffusion process

## 1. INTRODUCTION

A relevant change can be observed in the multimedia content generation, since common users are not long mere consumers and have become active producers. As a result, huge amounts of visual content have been accumulated daily, generated from a large variety of digital sources. The Content-Based Image Retrieval (CBIR) systems are considered a promising solution in this scenario, supporting searches capable of taking into account the visual properties of digital images.

The development of CBIR systems has been mainly supported by the creation of various visual features (based on shape, color, and texture properties) and different distance measures. However, more recently, research initiatives have focused on other stages of the retrieval process, which are not directly related to low-level feature extraction procedures. In several computer vision and image retrieval applications, capturing and exploiting the intrinsic manifold structure becomes a central problem for different vision, learning, and retrieval tasks [14].

Diverse methods also have been proposed in order to improve the effectiveness of distance measures in image retrieval tasks, specially based on diffusion approaches [14,

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15, 39, 40]. In general, these post-processing methods aims at replacing pairwise distances by more global affinity measures capable of considering the dataset manifold [40]. Although indispensable for improving the effectiveness of retrieval, the wide use of post-processing methods on largescale real-world applications also depends on efficiency and scalability aspects [24]. More recently, due to the high computational costs associated with diffusion-based approaches, other methods have emerged. Mainly based on rank analysis, such contextual rank measures [2, 26] can be efficiently computed.

In this paper, we propose a novel hybrid approach, named Rank Diffusion, which is based on a diffusion process defined in terms of ranking information. This method establishes a relationship between diffusion approaches and contextual rank measures in the sense it spreads ranking information, taking into account the dataset structure. A relevant contribution of the proposed approach is given in terms of efficiency aspects. Despite the use of a diffusion strategy, since only rank information is considered, low computational efforts are required.

An experimental evaluation was conducted, considering public datasets and several image descriptors, including global, local, and convolution-neural-network-based descriptors. Experiments were conducted on different retrieval tasks. The proposed method achieved significant effectiveness gains, yielding better results in terms of effectiveness performance than state-of-the-art approaches. For example, an accuracy score of 100% and a N-S score of 3.94 were achieved on the wellknown MPEG-7 [17] and UKBench [22] datasets.

# 2. RELATED WORK

In various multimedia and learning applications, objects are often modeled as high dimensional points in an Euclidean space. For retrieval or classification purposes, the distance between two objects is computed often considering the Euclidean distance. However, once pairwise distance measures define relationships only between pairs of images, the global structure of the dataset and the context wherein the query is computed are ignored. Therefore, how to capture and exploit the intrinsic manifold structure becomes a central problem in the vision and retrieval applications [14]. In this scenario, many approaches have been proposed [6, 9, 12, 14, 26, 28, 38, 39] to improve the effectiveness of image retrieval tasks. Such methods take into account the dataset manifold and the global relationships among images, without the need of any user intervention. Some of the most important diffusion- and rank-based methods.

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Diffusion-based approaches [7] rely on the definition of a global measure, which describes the relationship between pairs of points in terms of their connectivity. In general, diffusion processes consider as input a pairwise affinity matrix W, which can be interpreted as a graph that encodes the relationships among objects [9]. Let G = (V, E) be a graph, such as the nodes  $v_i \in V$  are associated with dataset objects and edges  $e_{ij} \in E$  indicate the existence of relationships among them. Edge weights, in turn, are defined by the affinity values  $w_{ij}$ . The matrix W is often computed by applying a Gaussian kernel to a distance matrix computed by an image descriptor [14]. Giving the edge weights [9] defined by the matrix W, the diffusion processes spread the affinities through the graph. In general, a walk in the graph occurs more likely through the edges with larger weights.

Several methods based on diffusion approaches have been proposed [9, 14, 38, 39]. The diffusion-based algorithms have been achieving significant improvements on retrieval performance although they are very expensive to compute, specially when the size of datasets becomes larger [2, 27].

Recently, various contextual rank-based approaches [2, 6, 26, 27, 29] have yielded very significant gains on retrieval effectiveness. Additionally, since the most relevant information of rankings is found at top positions, the rank-based approaches can significantly reduce the computational efforts required by exploiting indexing structures [24]. Therefore, other important requirements, such as efficiency and scalability [2, 24], are met.

In this paper, a novel hybrid re-ranking approach, which is based on a diffusion process defined in terms of ranking information, is presented. An advantage of the proposed method when compared with other approaches rely on its efficiency. As the diffusion process is based o rank information, only the top-ranked images can be considered.

## 3. FORMAL PROBLEM DEFINITION

This section formally defines the image retrieval and ranking model. Let  $C = \{img_1, img_2, \ldots, img_n\}$  be an image collection. The notation  $\rho(i, j)$  denotes the distance between two images  $img_i$  and  $img_j$  according to a given descriptor. Let  $img_q$  be a query image. A ranked list  $\tau_q$  can be computed in response to  $img_q$  based on the distance function  $\rho$ . The ranked list  $\sigma_q = (img_1, img_2, \ldots, img_n)$  can be defined as a permutation of the collection C. A permutation  $\sigma_q$  is a bijection from the set C onto the set  $[N] = \{1, 2, \ldots, n\}$ . For a permutation  $\sigma_q$ , we interpret  $\sigma_q(i)$  as the position (or rank) of image  $img_i$  in the ranked list  $\sigma_q$ .

The top positions of ranked lists are expected to contain the most similar images to the query image. Additionally,  $\sigma_q$ is expensive to compute, specially when n is high. Therefore, the computed ranked lists can consider only a sub-set of the images. Let  $\tau_q$  be a ranked list that contains only the L most similar images to  $img_q$ , where  $L \ll n$ . Formally, let  $\mathcal{C}_L$  be a sub-set of of the collection  $\mathcal{C}$ , such that  $\mathcal{C}_L \subset \mathcal{C}$  and  $|\mathcal{C}_L| = L$ . The ranked list  $\tau_q$  can be defined as a bijection from the set  $\mathcal{C}_L$  onto the set  $[N] = \{1, 2, \ldots, L\}$ . Every image  $img_i \in \mathcal{C}$ can be taken as a query image  $img_q$ . A set of ranked lists  $\mathcal{T}$  $= \{\tau_1, \tau_2, \ldots, \tau_n\}$  can also be obtained, with a ranked list for each image in the collection  $\mathcal{C}$ .

Our goal is to exploit the similarity information encoded in the set  $\mathcal{T}$ , with the aim of computing a more effective set  $\mathcal{T}_r$ . In fact, a more effective distance function  $\rho_r$  is defined, giving rise to a new set of ranked lists. Additionally, the fusion problem is also considered, in which different sets of ranked lists  $\{\mathcal{T}_1, \mathcal{T}_2, \ldots, \mathcal{T}_d\}$  are taken as input aiming at computing a more effective set  $\mathcal{T}_r$ .

#### 4. RANK DIFFUSION PROCESS

This section discusses and defines the proposed rank diffusion process, presenting each step involved in the method, until the computation of the rank-diffusion distance.

#### 4.1 Rank Similarity Matrix

Many diffusion-based algorithms use the distance information for defining a similarity matrix W. A Gaussian kernel is often considered, such that  $w_{ij} = exp(\frac{-\rho^2(i,j)}{2\sigma^2})$ , where  $\sigma$ is a parameter to be defined. Therefore, some strategies are required to define a suitable value for the parameter, also considering that the distance distribution may vary among different descriptors.

In this work, a rank similarity matrix W is proposed based only on rank information. The rank modeling of similarity information allows an uniform representation, independent of distance scores. The similarity score  $w_{ij}$  varies linearly according to the position of  $img_j$  in the ranked list  $\tau_i$ . Additionally, the score considers only a neighborhood set, which is defined by the size of ranked lists.

Let m denote the size of ranked lists and, therefore the neighborhood considered. Let  $\mathcal{N}(i,m)$  be the neighborhood set, which is formally defined as follows:

$$\mathcal{N}(i,m) = \{ \mathcal{R} \subseteq \mathcal{C}, |\mathcal{R}| = m \land \forall x \in \mathcal{R}, y \in \mathcal{C} - \mathcal{R} : \\ \rho(i,x) \leqslant \rho(i,y) \}.$$
(1)

The similarity rank matrix  $W_m$  is defined as:

$$w_{m_{ij}} = \begin{cases} m - \tau_i(j) + 1 & \text{if } img_j \in \mathcal{N}(i,m) \\ 0 & \text{otherwise.} \end{cases}$$
(2)

The size of the ranked list can assume different values depending on the desired analysis. In the proposed method, the matrix W is defined assuming  $m \leq k$ , for a local neighborhood analysis, and m = L for a more comprehensive collection sub-set. Notice that, since the matrix W has dimension of  $n \times n$ , both k and L values are much smaller than n, i.e,  $k, L \ll n$ . Therefore, the matrix W is very sparse. This property is exploited for defining an efficient algorithm, which computes operations that are equivalent to a matrix multiplication considering W.

#### 4.2 Reciprocal Rank Normalization

While most of similarity pairwise measures are symmetric, the same does not occur for rank measures. In other words, an image  $img_i$  well ranked for a query  $img_j$  does not imply that  $img_j$  is well ranked for query  $img_i$ . However, the benefits of improving the symmetry of the k-neighborhood relationship are remarkable in image retrieval applications [12]. Thus, a simple rank normalization procedure is conducted before the rank diffusion process. The reciprocal references among all ranked lists at top-L positions are considered, such m = L. For this, the similarity matrix  $W_L$  is used and its asymmetry is exploited. The value of  $w_{ij}$  is defined considering the position of  $img_j$  in the ranked list  $\tau_i$ , while  $w_{ji}$ considers the position of  $img_i$  in  $\tau_j$ . Therefore, a normalized rank similarity matrix  $\bar{R}_L$  can be defined as the sum of the original matrix W with its transposed:

$$\bar{R} = W_L + W_L^T. \tag{3}$$

Based on the matrix  $\bar{R}$ , a rank normalized distance  $\bar{\rho}$  is defined as:

$$\bar{\rho}(i,j) = \frac{1}{1+\bar{r}_{ij}},\tag{4}$$

where  $\bar{r}_{ij} \in \bar{R}$ .

In the following, all the ranked lists are updated according to the normalized distance, using a stable sorting algorithm. In this way, all similarity scores defined as 0 in the matrix  $\bar{R}$  have their distance changed to 1. In these cases, after the execution of the stable sorting algorithm, the previous order of ranked lists are maintained.

This update gives rise to a new set of ranked lists  $\overline{T}$ , used as input for the next steps of the proposed algorithm.

# 4.3 Iterative Rank Diffusion

The proposed rank diffusion approach is defined by an iterative update of similarity information encoded into a matrix P. The update at each iteration is computed according to a rank similarity matrix W of increasing neighborhood size. The central idea consists in spreading the similarity information through P considering initially a small neighborhood, which is gradually expanded over iterations. Therefore, the number of iterations is defined proportionally to the neighborhood size.

Formally, let  ${}^{(t)}$  denote the current iteration and let s be a constant value, which defines the initial neighborhood size. The rank similarity matrix at a given iteration t is defined as:

$$W^{(t)} = W_{s+t}.$$
(5)

where the size of ranked lists m = (s + t). The value of s = 2 can be used as a default starting value, or s can be manually defined. The initialization of matrix P is defined considering t = 0, and therefore:

$$P^{(0)} = W_s. (6)$$

Given the asymmetry rank relationships, a normalization similarity value is computed proportionally to the accumulated rank similarity of each image. The normalization is defined for matrices W and P, respectively as

$$\bar{W_{ij}}^{(t)} = \frac{W_{ij}^{(t)}}{\sum\limits_{i}^{n} W^{(t)}},$$
(7)

and

$$\bar{P}_{ij}^{(t)} = \frac{P_{ij}^{(t)}}{\sum_{c=1}^{n} P_{jc}^{(t)}}.$$
(8)

The iterative diffusion step is defined in terms of the multiplication of the normalized matrices  $\bar{P}$  and  $\bar{W}$ . At each iteration, a larger neighborhood is considered in  $\bar{W}$  and disseminated along P:

$$P^{(t+i)} = \bar{P}^{(t)} \bar{W^{(t)}}, \qquad (9)$$

where *i* indicates the increment (its default value is 1). The process is iteratively executed while  $t \leq (k - s)$ , where *k* is a parameter that defines the size of the neighborhood considered.

### 4.4 Reciprocal Rank Diffusion

The diffusion step defined in Equation 9 considers the transposed matrix  $W^{(t)}^{T}$ . In this way, the similarity of a given image  $img_i$  to other images is updated according to the ranked list  $\tau_i$  and is encoded in the similarity matrix.

However, the reciprocal similarity information should also be considered. With this purpose, after the iterative rank diffusion, a self-diffusion step is defined as:

$$P_r = \bar{P}^{(k-s)} \bar{P}^{(k-s)},$$
(10)

where  $\bar{P}^{(k-s)}$  represents the last matrix computed by the iterative diffusion after normalization.

#### 4.5 Rank Diffused Distance

Finally, a new rank diffused distance  $\rho_d$  is computed inversely proportional to the reciprocal similarity matrix  $P_r$ :

$$\rho_r(i,j) = \frac{1}{1 + P_{r_{ij}}} \tag{11}$$

Based on the distance  $\rho_r$ , the new and more effective set of ranked lists  $\mathcal{T}_r$  is computed using a stable sorting algorithm. As for the rank normalization step, images, which present similarity values equal to 0, maintain the previous order in the ranked lists.

# 5. RANK AGGREGATION

Different features often encode distinct and complementary visual information extracted from images. Therefore, if a feature produces effective rankings by itself and is complementary (heterogeneous) to other features, then it is expected that a higher search accuracy can be achieved by combining them [42].

In this work, a rank aggregation approach is presented for combining different rankings using the proposed rank diffusion process. The rank diffusion is performed in two stages: first, for each descriptor in isolation and in the next, considering a fused set of ranked lists.

Let  $\mathcal{D} = \{D_1, D_2, \dots, D_d\}$  be a set of different image descriptors and let  $\{\mathcal{T}_1, \mathcal{T}_2, \dots, \mathcal{T}_d\}$  be their respective set of ranked lists. The rank diffusion process is computed for each set  $\mathcal{T}_i$ , in order to compute a matrix  $P_r$  (Equation 10). In the following, a fused matrix  $P_f$  is defined as:

$$P_f = \sum_{j \in \mathcal{D}} P_{r_j}.$$
 (12)

Based on  $P_f$ , a new distance  $\rho_f$  is computed:

$$\rho_f(i,j) = \frac{1}{1 + P_{f_{ij}}}.$$
(13)

A fused set of ranked lists  $\mathcal{T}_f$  is computed using the distance  $\rho_f$ . Finally, we aim at exploiting the contextual information of the fused set of ranked lists  $\mathcal{T}_f$ . Once the set  $\mathcal{T}_f$  presents the same structure of a set obtained for a single descriptor, it is submitted to the regular rank diffusion process, giving rising to a final set  $\mathcal{T}_r$ .

## 6. EXPERIMENTAL EVALUATION

The proposed method was evaluated on shape and natural image retrieval tasks, considering the MPEG-7 [17] and UKBench [22] datasets, which are commonly used as benchmark for image retrieval and post-processing methods. All images of each dataset are used as query images. Regarding parameters, we used s=5, i=5, and k=20 for the MPEG-7 [17] dataset and s=2, i=2, and k=6 for the UKBench [22] dataset, due to the small number of images per class.

#### 6.1 Shape Retrieval

The shape retrieval experiments were condcuted on the MPEG-7 [17], which is a well-known shape dataset, com-

posed of 1400 shapes divided into 70 classes. Six shape descriptors were considered and the *Mean Average Precision* (MAP) was used as effectiveness measure.

Table 1 presents the experimental results for shape retrieval experiments. Statistical paired t-tests were conducted comparing the results before and after the use of the proposed algorithm. Different values of L are considered: L =400 and the whole ranked list. Positive gains with statistical significance can be observed for all descriptors, reaching high effectiveness gains up to +40.72%. The effectiveness results obtained for partial and the entire ranked lists are very similar, demonstrating that only a sub-set of ranked lists is enough to obtain high effectiveness gains.

Results for rank aggregation tasks are also presented considering the combination of the three best descriptors. The relative gains are computed based on the descriptor with the lowest MAP score. As it can be observed, high effective results are also obtained, reaching 99.78% for CFD+AIR.

Table 1: Rank Diffusion for shape retrieval tasks (MAP as score).

	Orig.		L = 400		Full L			
Descriptor	MAP	Rank Diff.	Gain	Stat. Sig.	Rank Diff.	Gain	Stat. Sig.	
SS [8]	37.67%	52.17%	+38.49%	٠	53.01%	+40.72%	•	
BAS [1]	71.52%	82.36%	+15.16%	•	83.03%	+16.09%	•	
IDSC [18]	81.70%	90.89%	+11.25%	•	91.09%	+11.49%	•	
CFD [25]	80.71%	93.75%	+16.16%	•	94.17%	+16.68%	•	
ASC [19]	85.28%	92.98%	+9.03%	•	93.07%	+9.13%	•	
AIR $[10]$	89.39%	97.98%	+9.61%	•	97.97%	+9.60%	•	
CFD+ASC	-	99.29%	+23.02%	•	99.25%	+22.97%	•	
ASC+AIR	-	99.57%	+16.76%	•	99.58%	+16.77%	•	
CFD+AIR	-	99.78%	+23.63%	•	99.79%	+23.64%	•	

#### 6.2 Natural Image Retrieval

We evaluate the proposed method in natural image retrieval tasks considering the University of Kentucky Recognition Benchmark – UKBench [22]. The UKBench dataset has a total of 10,200 images, composed of 2,550 objects or scenes, where each object/scene is captured 4 times from different viewpoints. The small number of images per class constitutes a challenging scenario for unsupervised learning approaches. Various distinct features are used, including color and color/texture features available on LIRE framework [20]. Local features are considered based on Vocabulary Tree (VOC) [36]. Convolution neural networks (CNN) features based on Caffe [13] framework are also considered.

Table 2 presents the effectiveness results considering the UKBench [22] dataset. The N-S score is used as effectiveness measure, varying between 1 and 4. This score corresponds to the number of relevant images among the first four image returned (the highest achievable score is 4). We can observe significant improvements for N-S scores. Notice, for example, the Caffe [13] convolutional neural network, which is improved from 3.31 to 3.61. The results are even more impressive considering the rank aggregation tasks.

## 6.3 Comparison with Other Approaches

The proposed method is also evaluated in comparison with various other state-of-the-art approaches and recently proposed retrieval approaches. Table 3 presents the results of Rank Diffusion method on the UKBench [22] dataset in comparison with recent retrieval approaches. Table 4 presents the obtained results on the MPEG-7 [17] dataset in comparison with various other state-of-the-art post-processing methods. The bull's eye score, which counts the matching

Table 2: Rank Diffusion on the UKBench [22] dataset.

	Original	Rank
Descriptor	N-S	Diffusion
CEED-SPy $[4, 20]$	2.81	3.10
FCTH-SPy [5, 20]	2.91	3.19
SCD [21]	3.15	3.35
ACC-SPy [11, 20]	3.25	3.51
CNN-Caffe [13]	3.31	3.61
ACC [20]	3.36	3.60
VOC [36]	3.54	3.72
VOC+ACC	-	3.90
VOC+CNN	-	3.90
ACC+CNN	-	3.87
VOC+ACC+CNN	-	3.94

shapes within the top-40 ranked images, is used as evaluation measure. As it can be observed, the effectiveness results of the proposed method compares favorably with the recent retrieval approaches.

Table 3: Retrieval comparison on the UKBench [22] dataset.

	N-5	5 score	es for re	ecer	nt retrieva	l method	s		
Zheng	g Qin		Wang		Zhang	Zheng		Xie	
et al. [43]			et al. [34]		et al. [41]	et al. [4	2]	2] et al. [3	
3.57	3.67		3.68		3.83	3.84		3.89	
				_				-	
					nk Diffus				
					ank Diff.	Rank Diff.			
ACC+CNN		VOC+CNN		VOC+ACC		VOC+ACC+CNN			
3.88		3	3.90		3.90	3.94		L	
Tabl	le 4:	Comp			the MPE	G-7 [17] d	ata	aset.	
			Shape	De	scriptors			1.43%	
CFD [25]					-	-			
IDSC [18]				-		85.40% 88.39%			
ASC [19]				-	-				
AIR [10]			-		93.67%				
		Pos	t-Proc	essi	ng Meth	ods			
Algorithm			Desc	Descriptor(s)		Score			
Graph Transduction [38]				IDSC		91.00%			
Locally C. Diffusion Process [39]				9] IDSC	IDSC		93.32%		
Shortest Path Propagation [35]				] IDSC	IDSC		93.35%		
Locally C. Diffusion Process [39]				9] ASC	ASC		95.96%		
Rank Diffusion				CFD	CFD		96.19%		
Tensor Product Graph [40]				AIR	AIR		99.99%		
Generic Diffusion Process [9]				AIR	AIR		100%		
Neighbor Set Similarity [2]				AIR	AIR		100%		
Neighbo	Rank Diffusion						100%		

# 7. CONCLUSIONS

Post-processing procedures based on unsupervised learning approaches have been established as indispensable tools for improving the effectiveness of CBIR systems. Since diffusion process methods require high computational efforts, rank-based approaches attracted a lot of research attention recently to circumvent their limitations. In this paper, a novel rank diffusion method is proposed exploiting characteristics of both diffusion and rank-based approaches. A rigorous experimental evaluation demonstrated the effectiveness of the proposed approach. Future work focuses on the deep investigation of contextual information encoded in the rank similarity matrix.

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