Image Processing using Graphs (lecture 5 - clustering and classification)

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- We need more efficient and effective pattern recognition methods for large datasets.
- The applications are in many fields of the sciences and engineering.
- Our main focus has been on image analysis.

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- In supervised learning, a labeled set $\mathcal{T} \subset \mathcal{Z}$ is available to train the classifier.
- In unsupervised learning, there is no knowledge about the labels in $\mathcal{T}$. Clusters can be found and class labels may be assigned to them based on some prior knowledge.

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- the probability density function of the classes/clusters presents known shapes for parametric modeling.

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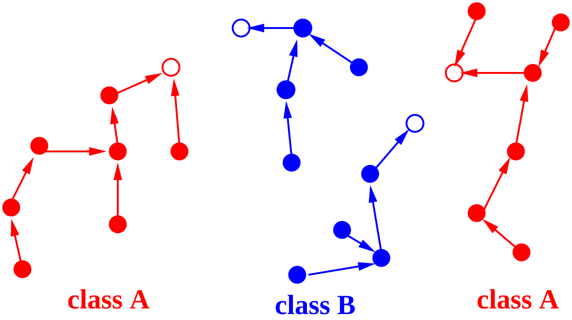
- A connectivity function $f(\pi_t)$ assigns a value to any path π_t from its root $R(\pi_t)$ to its terminal node t.
- The minimization (maximization) of the connectivity map

$$V(s) = \min_{\forall t \in \Pi(\mathcal{T}, \mathcal{A}, t)} \{f(\pi_t)\}$$

produces an optimum-path forest rooted at nodes called prototypes.

Introduction

In supervised learning, each class is an optimum-path forest rooted at its prototypes, which propagate the class label to the remaining nodes of the forest.



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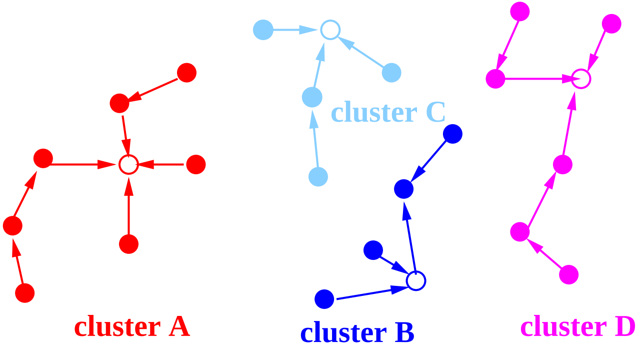

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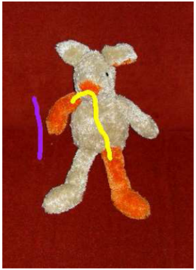
- Both learning approaches are fast and robust for training sets of reasonable sizes.
- Label propagation to new samples $t \in \mathcal{Z} \backslash \mathcal{T}$ is efficiently performed based on a local processing of the forest's attributes and distances between nodes $s \in \mathcal{T}$ and t.

Organization of this lecture



- Supervised classification by OPF [1].

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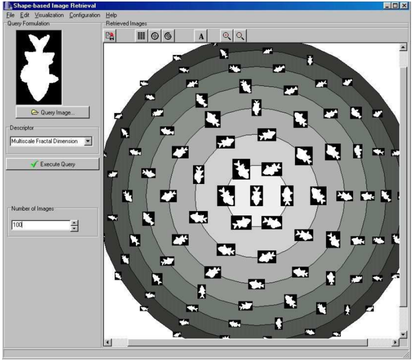

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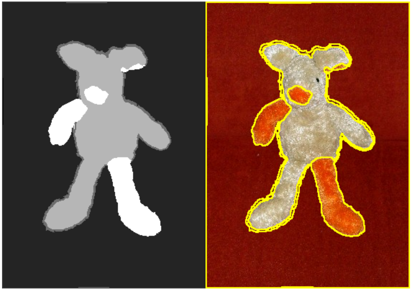

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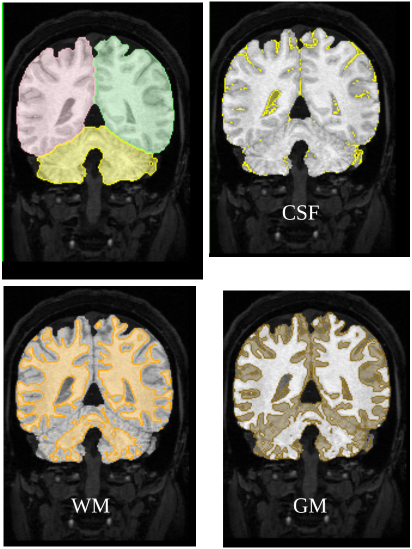

- Supervised classification by OPF [1].
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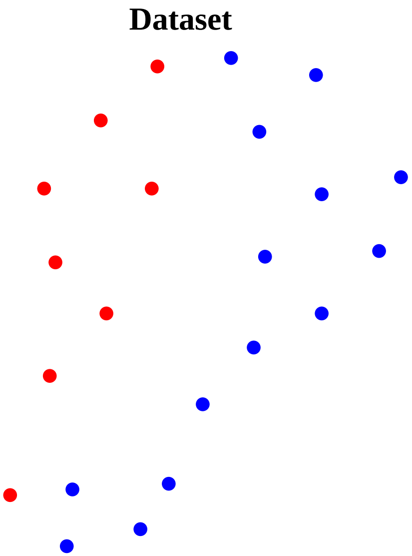
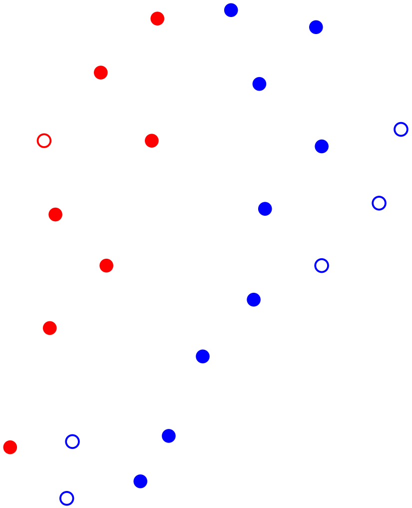
- Clustering by OPF [3].
- Its application to 3D brain tissue segmentation [4].



- Consider samples from two classes of a dataset.

Training



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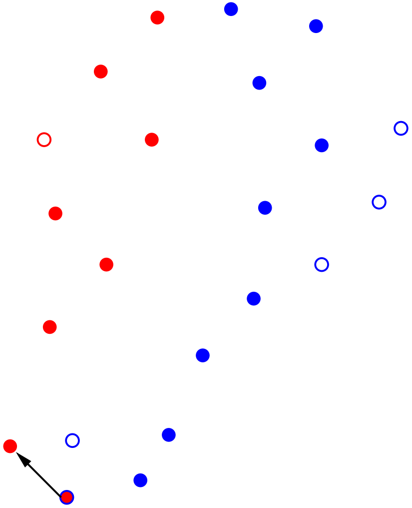
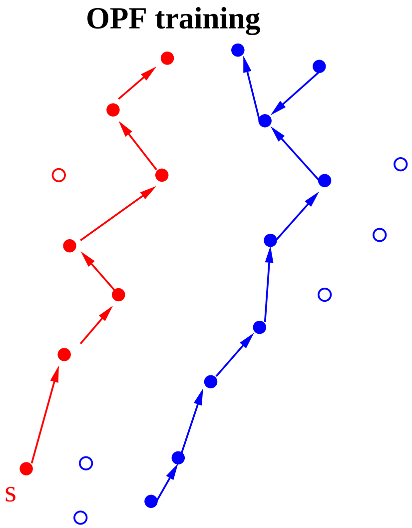
- A training set (filled bullets) may not represent the data distribution.

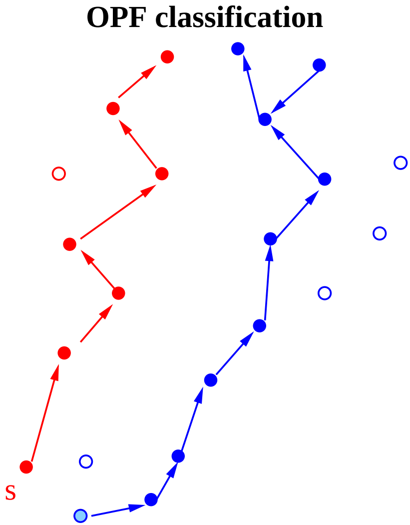
1NN classification



- Consider samples from two classes of a dataset.
- A training set (filled bullets) may not represent the data distribution.
- Classification by nearest neighbor fails, when training samples are close to test samples (empty bullets) from other classes.



- We can create an optimum-path forest, where $V(s)$ is penalized when s is not closely connected to its class.



- We can create an optimum-path forest, where $V(s)$ is penalized when s is not closely connected to its class.
- $V(s)$ can then be used to reduce the power of s to classify new samples.

Supervised learning

- We interpret $(\mathcal{T}, \mathcal{A})$ as a complete graph with undirected arcs between training samples.

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- For a given set $\mathcal{S} \subset \mathcal{T}$ of prototypes from all classes, the connectivity map $V(t)$ is minimized for

$$
\begin{aligned}
f_{\max}(\langle t \rangle) &= \begin{cases} 0 & \text{if } t \in \mathcal{S} \\ +\infty & \text{otherwise} \end{cases} \\
f_{\max}(\pi_s \cdot \langle s, t \rangle) &= \max\{f_{\max}(\pi_s), d(s,t)\}
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where $d(s,t)$ is the distance between s and t as computed by a descriptor.

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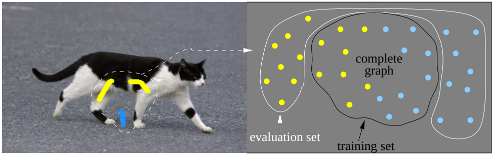
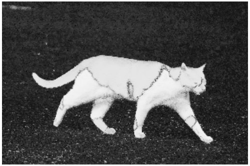
  where $d(s,t)$ is the distance between s and t as computed by a descriptor.
- The prototypes are the closest samples between classes.

Supervised learning

We used this idea to enhance objects in lecture 3 where $\mathcal{Z} = \mathcal{D}_I$.





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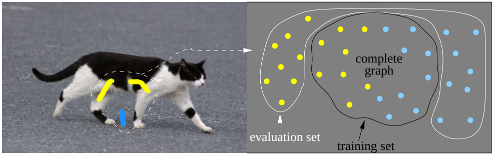
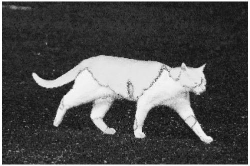
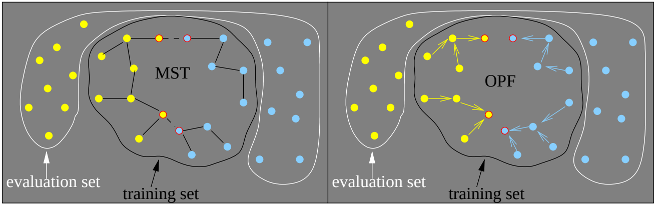
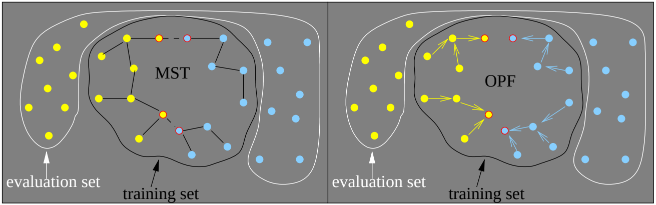




Even marker nodes may constitute large labeled sets, but they can be divided into a smaller training set $\mathcal{T}$ and a larger evaluation set $\mathcal{E}$ such that the most representative samples for $\mathcal{T}$ can be learned from $\mathcal{E}$.

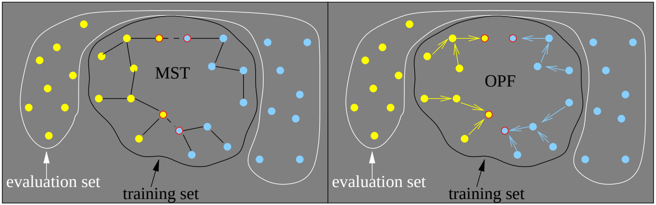
Supervised learning





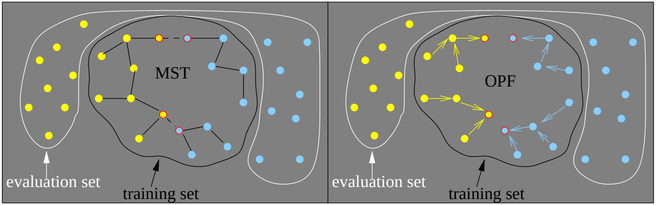
- A minimum spanning tree is computed in $(\mathcal{T}, \mathcal{A})$ and nodes that share arcs between distinct classes are taken as prototypes in $\mathcal{S}$.

Supervised learning



- A minimum spanning tree is computed in $(\mathcal{T}, \mathcal{A})$ and nodes that share arcs between distinct classes are taken as prototypes in $\mathcal{S}$.
- Object and background are then represented by optimum-path forests rooted in $\mathcal{S}$ (i.e., a pixel classifier).

Supervised learning



- Prototypes compete among themselves and nodes in the evaluation set $\mathcal{E}$ are classified in the tree whose prototype offers an optimum path to it.

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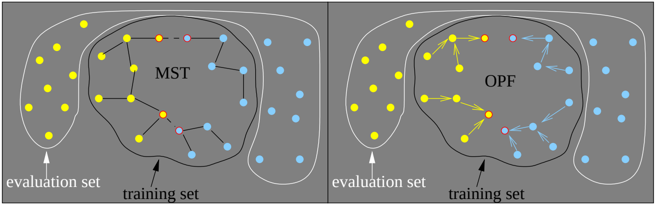

- Prototypes compete among themselves and nodes in the evaluation set $\mathcal{E}$ are classified in the tree whose prototype offers an optimum path to it.
- Misclassified nodes in $\mathcal{E}$ are replaced by non-prototypes in $\mathcal{T}$ and the whole process is repeated for a few iterations in order to select the most representative nodes for $\mathcal{T}$.

Classification

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- Let $s^* \in \mathcal{T}$ be the node that satisfies this equation, then the class of t is assumed to be $L(s^*)$.
- Let $V_o(t)$ and $V_b(t)$ be the optimum values in the above equation for object and background forests, then a fuzzy object membership $\frac{V_b(t)}{V_o(t)+V_b(t)}$ can be assigned to every spel $t \in \mathcal{D}_I$.

Supervised OPF-training algorithm

Algorithm

– SUPERVISED TRAINING BY OPTIMUM-PATH FOREST

For each $t \in \mathcal{T} \backslash \mathcal{S}$, *set* $V(t) \leftarrow +\infty$.
For each $t \in \mathcal{S}$, *set* $L(t) \leftarrow \lambda(t)$, $V(t) \leftarrow 0$ *and insert* t *in* Q.
While Q *is not empty, do*
    Remove from Q *a node* s *such that* $V(s)$ *is minimum.*
    Insert s *in* $\mathcal{T}'$.
    For each $t \in \mathcal{T}$ *such that* $V(t) > V(s)$, *do*
        Compute $tmp \leftarrow \max\{V(s), d(s,t)\}$.
        If $tmp < V(t)$, *then*
            If $V(t) \neq +\infty$, *remove* t *from* Q.
            Set $V(t) \leftarrow tmp$ *and* $L(t) \leftarrow L(s)$.
            Insert t *in* Q.

The role of the ordered set $\mathcal{T}'$ is to speed up classification [5], which can halt when $\max\{V(s), d(s,t)\} < V(s')$ for a node s' whose position in $\mathcal{T}'$ succeeds the position of s, while evaluating

$$V(t) = \min_{\forall s \in \mathcal{T}'} \{\max\{V(s), d(s,t)\}\}.$$

Prototype estimation

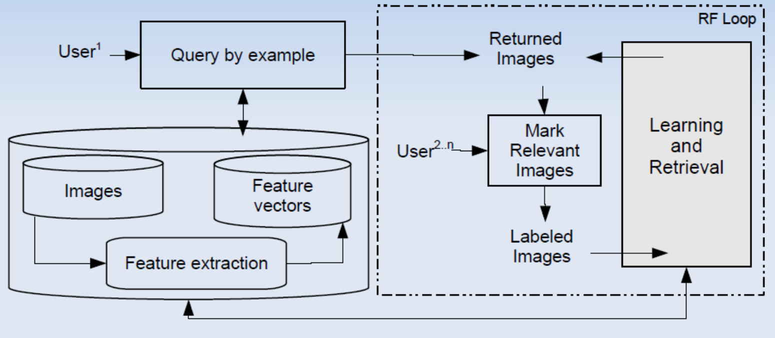
The minimum spanning tree can be obtained from the same algorithm by

- using a non-smooth function

$$
\begin{aligned}
f_{mst}(\langle t\rangle) &= \begin{cases} 0 & \text{for an arbitrary node } t \in \mathcal{T} \\ +\infty & \textit{otherwise}, \end{cases} \\
f_{mst}(\pi_s \cdot \langle s, t\rangle) &= w(s,t),
\end{aligned}
$$

- and replacing $V(t) > V(s)$ in Line 6 by $V(t) = +\infty$ or $t \in Q$.

The OPF classifier has provided effective and efficient image retrieval from a few iterations of relevance feedback.



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- The relevant candidates are ordered based on their average distances to the relevant prototypes.

For a query image using the Corel database and the BIC image descritor [6].

Application to Image Retrieval

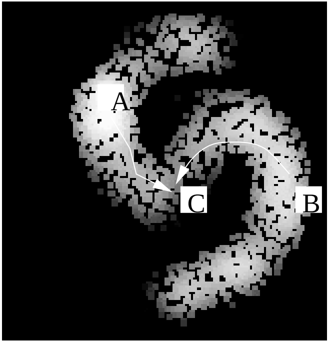
First iteration only returns the 30 closest images to the query one.

Application to Image Retrieval

After three iterations, the 30 most relevant images are.

Clustering

For unsupervised learning, we estimate a probability density function (pdf) and the maxima of the pdf compete with each other, such that each cluster will be an optimum-path tree rooted at one maximum of the pdf.



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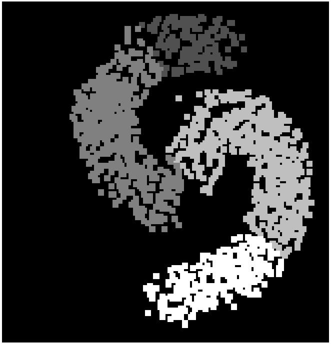

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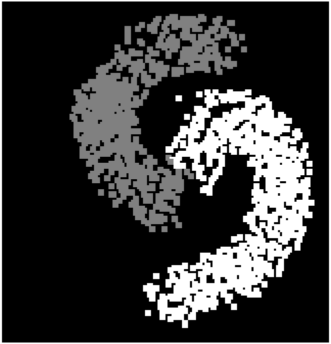


It is also possible to eliminate clusters of irrelevant maxima by choice of the connectivity function.

The unlabeled training samples form a knn-graph $(\mathcal{T}, \mathcal{A}_k)$ with adjacency relation

$$\mathcal{A}_k \quad : \quad (s,t) \in \mathcal{A}_k \text{ (or } t \in \mathcal{A}_k(s)) \text{ if } t \text{ is } k \text{ nearest neighbor of } s \text{ using the distance space.}$$

The best value of k is the one whose clustering produces a minimum normalized graph cut in $(\mathcal{T}, \mathcal{A}_k)$.

The graph is weighted on the arcs $(s,t) \in \mathcal{A}_k$ by $d(s,t)$ and on the nodes by the pdf $\rho(s)$.

$$\rho(s) = \frac{1}{\sqrt{2\pi\sigma^2}|\mathcal{A}_k(s)|} \sum_{\forall t \in \mathcal{A}_k(s)} \exp\left(\frac{-d^2(s,t)}{2\sigma^2}\right)$$

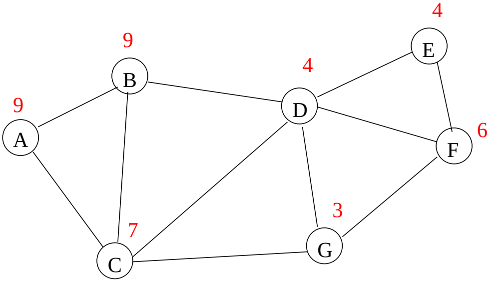
where $\sigma = \frac{d_f}{3}$ and $d_f = \max_{\forall (s,t) \in \mathcal{A}_k}\{d(s,t)\}$. The pdf is usually normalized within an interval $[1, K]$.

The connectivity map $V(t)$ is maximized for

$$
\begin{aligned}
f_{\min}(\langle t\rangle) &= \begin{cases} \rho(t) & \text{if } t \in \mathcal{R} \\ \rho(t) - 1 & \text{otherwise} \end{cases} \\
f_{\min}(\pi_s \cdot \langle s, t\rangle) &= \min\{f_{\min}(\pi_s), \rho(t)\}
\end{aligned}
$$

where $\mathcal{R}$ is the root set found on-the-fly and arcs are added in $\mathcal{A}_k$ to guarantee arc symmetry on the plateaus of the pdf.

Optimum-path forest for $f_{\min}$.



Prototype set $\mathcal{S} = \{A, F\}$ is found on-the-fly.

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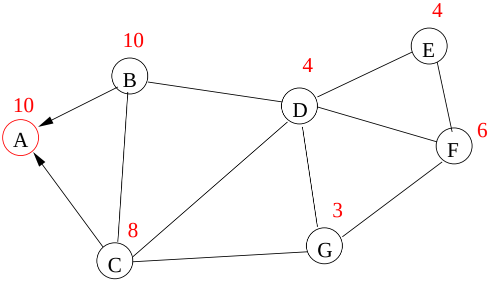

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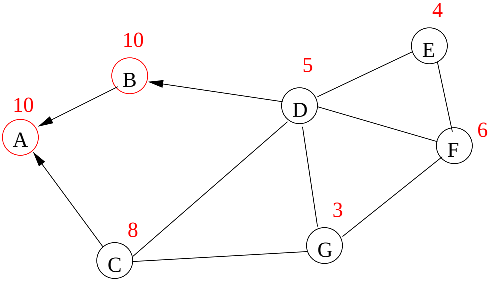

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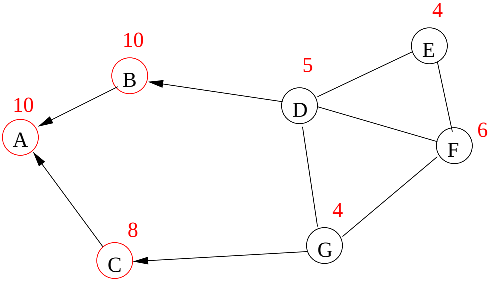

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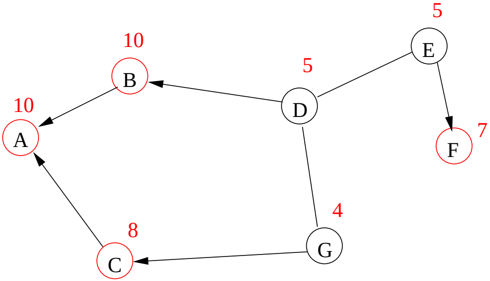

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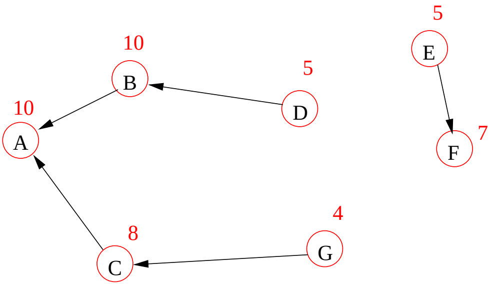

Prototype set $\mathcal{S} = \{A, F\}$ is found on-the-fly.

OPF-clustering algorithm

Algorithm

– Clustering by Optimum Path Forest

```
Set lb ← 1.
For each s ∈ 𝒯, set V(s) ← ρ(s) − 1 and insert s in Q.
While Q is not empty, do
    Remove from Q a sample s such that V(s) is maximum
    Insert s in 𝒯′.
    If P(s) = nil, then
        Set L(s) ← lb, lb ← lb + 1, and V(s) ← ρ(s).
    For each t ∈ 𝒜_k(s) and V(t) < V(s), do
        Compute tmp ← min{V(s), ρ(t)}.
        If tmp > V(t) then
            Set L(t) ← L(s) and V(t) ← tmp.
            Update position of t in Q.
```

The role of the ordered set $\mathcal{T}'$ is to speed up label propagation to new nodes $t \in \mathcal{Z} \backslash \mathcal{T}$ [4], which can halt when s^* is found in

$$V(s^*) = \max_{\forall s \in \mathcal{T}' | d(s,t) \leq \omega(s)} \{V(s)\},$$

where $\omega(s)$ is the maximum distance between s and its k-nearest neighbors in $\mathcal{T}$. The node t then receives label $L(s^*)$.

Application to brain tissue segmentation

After brain segmentation and bias correction.

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- The brain voxels are first classified into CSF or GM+WM and then classified into GM or WM, because the method requires different parameters (e.g., different features and $\mathcal{A}_k$) in each case.

Application to brain tissue segmentation

After brain segmentation and bias correction.

- The brain voxels are first classified into CSF or GM+WM and then classified into GM or WM, because the method requires different parameters (e.g., different features and $\mathcal{A}_k$) in each case.
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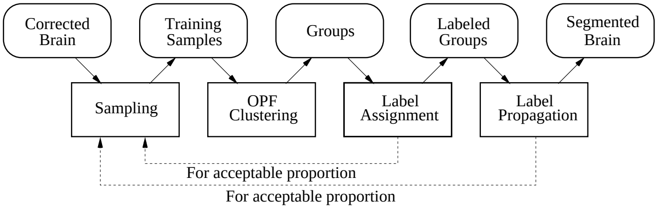
- The process may be repeated until it achieves an acceptable result.

Brain tissue segmentation



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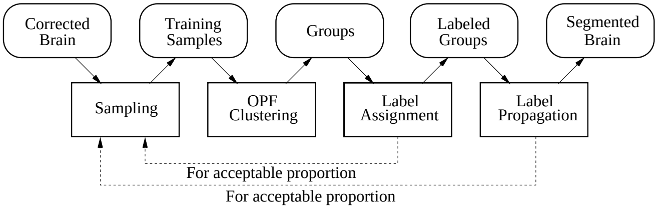

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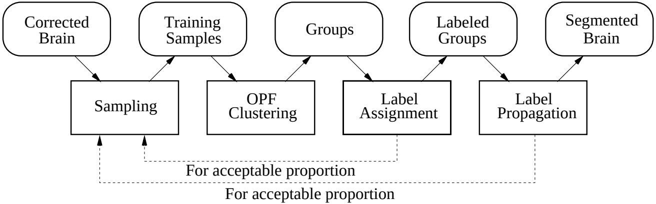

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- The acceptance criterion requires that $p \in [p_T - \delta, p_T + \delta]$, whose value of δ increases at every m sampling attempts.

Conclusion

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- These methods have been succeeded not only in image retrieval [2] and medical imaging [4], but also in several other applications.
- Their C source code is available in `www.ic.unicamp.br/~afalcao/libopf`.

Acknowledgments

- FAPESP.
- The organizing committee.
- My students and other collaborators.
- You all for the participation.

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