MO434 - Deep Learning Convolutional Neural Networks

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- Convolutional neural network (CNN).
- Building a CNN model for image classification.
- Classical modules to enhance CNN models.
- Using and fine-tuning pretrained models.
- How to explain CNNs using information visualization.

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- David Hubel and Torsten Wiesel (Nobel Prize in Medicine, 1981) showed that
 - some neurons react to small receptive fields (adjacency relations),
 - others with a same receptive field react to lines of different orientations (filters of a kernel bank), and
 - neurons with larger receptive fields react to more complex patterns (small adjacency relations in deeper layers correspond to larger regions in the input image).

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 - neurons with larger receptive fields react to more complex patterns (small adjacency relations in deeper layers correspond to larger regions in the input image).
- From lower- to higher-level image patterns can be extracted by stacking more convolutional layers – a feature extractor.

- Yann LeCun proposed LeNet-5 (1998) by adding pooling and normalization to convolutional layers.
- The ImageNet dataset (Fei-Fei Li, 2009) accelerated the development and success of several other CNNs, starting with AlexNet (Alex Krizhevsky, 2012).
- Such convolutional layers (CL) have much less parameters than dense layers (DL), which finally makes training by backpropagation feasible for deep neural networks.



A convolutional layer may contain convolution, activation, pooling, normalization, skip connections, and subnetworks (modules/layer blocks) – e.g., LeNet-5, AlexNet, and VGGNet.



By flattening or by global average pooling, its output becomes a global feature vector for the input of the first dense layer.

GoogLeNet (Christian Szegedy et al., 2015) incorporated inception modules to CNNs.



A depth concatenation layer concatenates the output of multiple convolutional layers $w \times w + s$, with $w \times w$ adjacencies, padding w/2, and stride s.

ResNet (Kaiming He et al., 2015) incorporated residual modules, whose goal is to force a residual output f(x) = h(x) - x for an input x that passes through a subnetwork of output h(x).



CO+BN+RE is convolution followed by batch normalization and ReLU.

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- SENet (Jie Hu et al., 2018) added squeeze-and-excitation module to recalibrate feature maps from another module.



An SE module outputs the importance in [0, 1] of each channel at the output of a given module (inception/residual).

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- Class separability: convolutional layers aim to map images of distinct classes onto different subspaces, such that the classes can be separated by one or two dense layers.
- Neuron specialization: the goal of hidden dense layers is to reduce dimensionality and specialize neurons as the faces of one hyperpolyhedron per class (see Fundamentals of DNNs -Part I).

Deeper convolutional layers should increase class separability.



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Neuron specialization



Neuron projections (MDS, right) colored by their discriminative power for class 8 versus the others in a digit dataset.

How to

- specify operations such as convolution, activation, pooling, batch normalization and skip connections,
- build a simple CNN for image classification,
- train and test our model, and
- save the model for future use (Building a simple CNN).

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Let's build, train, and test a more complex CNN for image classification. We will

• build models from scratch (Building models from scratch) and

• use pretrained models to extract features for image classification • (Using pre-trained models).

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Explaining CNNs with information visualization

 How to visualize activations and the importance of image regions in a model decision

 (Explaining the model).

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• The next lecture will introduce CNN applications to image analysis and your project in this course.

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